

# ON SOME FIXED POINT RESULTS IN GENERALIZED METRIC SPACE WITH SELF MAPPINGS UNDER THE BOUNDS

## **Rohit Kumar Verma**

Associate Professor, Department of Mathematics, Bharti Vishwavidyalaya, Durg, C.G., India.

\*\*\*\_\_\_\_\_\_

#### Abstract

Generalized metric spaces are important in many fields and are regarded as mathematical tools. The idea of generalized metric space is introduced in this study, and various sequence convergence qualities are demonstrated. We also go over the continuous and self mappings fixed point extended result.

**Keyword:** Generalized metric spaces, Continuous mappings, Self mappings, Fixed point theory.

## **1. INTRODUCTION**

The study of fixed point theory has been at the center of vigorous activity, although they arise in many other areas of mathematics. In 1992, Dhage [1] developed the concept of generalized metric space, often known as D-metric space, and demonstrated the existence of a single fixed point for a self-map that satisfies a contractive condition. Rhoades [4] discovered certain fixed point theorems and generalized Dhage's contractive condition. The Rhoades contractive condition was also extended by Dhage's [3] to two maps in D-metric space. Dhage [2] discovered a singular common fixed point [6] on a D-metric space by applying the idea of weak compatibility of self-mappings.

A generalized metric on set X is a function  $D: X \times X \times X \to R_+$  such that for any  $x, y, z, w \in X$  (*i*)  $D(x, y, z) \ge 0$  and D(x, y, z) = 0 if and only if x = y = z, (*ii*) D(x, y, z) = D(p(y, x, z)), where *p* is a permutation, and (*iii*)  $D(x, y, z) \le D(x, y, a) + D(x, a, z) + D(a, y, z)$ . The pair (*X*, *D*) is referred to be generalized metric space after that. A triangle with the vertices *x*, *y* and *z* has a peridiameter defined by a generalized metric D(x, y, z).

**Definition 1.1** If  $R(a, b, c) = \max(a, b, c)$  then  $D(x, y, z)(p + q + r) \le R(D(x, y, a)(p), D(x, a))$ 

 $(z)(q), D(a, y, z)(r) \Leftrightarrow \tau_a(x, y, z) \le \tau_a(x, y, a) + \tau_a(x, a, z) + \tau_a(a, y, z) \text{ for all } \alpha \in [0,1] \text{ and } x, y, z \in X.$ 

**Definition 1.2** If  $S(a, b, c) = \min(a, b, c)$  then  $D(x, y, z)(p + q + r) \ge S(D(x, y, a)(p), D(x, a))$ 

 $(z)(q), D(a, y, z)(r) \Leftrightarrow \varepsilon_a(x, y, z) \le \varepsilon_a(x, y, a) + \varepsilon_a(x, a, z) + \varepsilon_a(a, y, z) \text{ for all } \alpha \in [0,1] \text{ and } x, y, z, a \in X.$ 

**Definition 1.3** A sequence  $\{x_n\}$  in a D-metric space is said to be Cauchy if for any given  $\epsilon > 0$ , there exists  $n_0$  such that for all  $r, s, t > n_0, D(x_r, x_s, x_t) < \epsilon$ .

**Definition 1.4** *f* is said to be orbitally continuous if for each  $x \in X$ ,  $\{x_n\} \subset O_f(x), x_n \to x^* \Rightarrow$ 

 $fx_n \to fx^*. O_f(x) = \{x\} \cup \{f^n x : n \in N\}.$ 

**Theorem 1.5** Let (X, D) be a complete bounded D-metric space and T be a self map of X satisfying the condition that if there exists a  $k \in [0, 1)$  such that for all  $x, y, z \in X$  if

 $D(Tx, Ty, Tz) \le k \max\{D(x, y, z), D(x, Tx, z), D(y, Ty, z), D(x, Ty, z), D(y, Tx, z)\}.$ 

Then *T* has a unique fixed point *u* in *X* and *T* is continuous at *u*.

**Theorem 1.6** Let (X, D) be a compact D-metric space and T be a continuous self map of X satisfying for all  $x, y, z \in X$  with  $D(x, y, z) \neq 0$ ,

 $D(Tx, Ty, Tz) < \max\{D(x, y, z), D(x, Tx, z), D(y, Ty, z), D(x, Ty, z), D(y, Tx, z)\}.$ 

Then *T* has a unique fixed point  $u \in X$ .

**Definition 1.7** Let *T* represent a multi-valued map [7] on the (X, D) D-metric space. Let  $x_0 \in X$ . If  $x_{n-1} \in T^{n-1}(x_0)$ , then  $x_n \in Tx_{n-1}$ ,  $\forall n \in N$ , then a sequence  $\{x_n\}$  in *X* is said to represent an orbit of *T* at  $x_0$  denoted by  $O(T, x_0)$ . If an orbit's diameter is finite, it is said to be bounded. If every Cauchy sequence in it converges to a point on *X*, then it is said to be complete.

 $D(x, y, z) = \max[\phi(x, y), \phi(x, z), \phi(y, z)]$  is an example [5] of D-metric., where  $\phi$  is a metric on X, and (b)  $D(x, y, z) = \phi(x, y) + \phi(x, z) + \phi(y, z)$ .

When a sequence  $\{x_n\}$ ,  $\lim_{n\to\infty} x_n = x$  in a D-metric space (X, D) converges to a point x, it is said to be D-convergent. If there is an  $n_0 \in N$  such that  $D(x_n, x_m, x) < \delta \forall n, m > n_0$ .

If  $\phi_m[(s_1, s_2, s_3, s_4, s_5), s_6] = \phi[\max(s_1, s_2, s_3, s_4, s_5)] - s_6$  and  $\phi_m: R_+^5 \times R_+ \to R_+$  In this case,  $\phi: R_+ \to R_+$  is a non-decreasing upper semi-continuous function with  $\phi(0) = 0$  and  $\phi(s) < s$  for s > 0. Then, on  $R_+^5 \times R_+$ ,  $\phi_m$  is upper semi-continuous, and  $\phi_m$  is non-decreasing on  $R_+^5$ . Additionally,  $\phi_m[(p, p, p, p, p), q] \ge 0 \Rightarrow q \le \phi(p)$ . Therefore,  $\phi_m \in \phi$ .

## 2. OUR RESULTS

**Theorem 2.1** If (X, D) is a complete generalized metric space with three self-mappings of X that satisfy the criterion  $T_1, T_2$  and  $T_3$  such that

 $D(T_1x, T_2y, T_3z) \le \beta_1 \max[D(y, T_1x, T_2y), D(y, T_2y, T_3z), D(y, T_3z, T_1x)]$ 

 $+\beta_2 \max[D(x, T_2y, T_3z), D(x, y, z), D(y, T_2y, T_3z)] + \beta_3 D(x, T_1x, T_2y)$ 

For all  $x, y, z \in X$  and  $\beta_1, \beta_2, \beta_3 \in R$  satisfying the condition  $3\beta_1 + 3\beta_2 < 1 - \beta_3$ . Then *T* has fixed point.

**Proof:** Let  $x_0 \in X$  and define a sequence  $\{x_n\}$  of points of  $X: T_1x_{2n} = x_{2n+1}, T_2x_{2n+1} = x_{2n+2}, T_3x_{2n+2} = x_{2n+3}, n = 0, 1, ... ...$ Now, applying the given condition we achieve the result as follows  $D(T_1x_{2n}, T_2x_{2n+1}, T_3x_{2n+2}) = D(x_{2n+1}, x_{2n+2}, x_{2n+3})$ 

 $\leq \beta_1 \max[D(x_{2n+1}, x_{2n+1}, x_{2n+2}), D(x_{2n+1}, x_{2n+2}, x_{2n+3}), D(x_{2n+1}, x_{2n+3}, x_{2n+1})] +$ 

 $\beta_2 \max[D(x_{2n}, x_{2n+2}, x_{2n+3}), D(x_{2n}, x_{2n+1}, x_{2n+2}), D(x_{2n+1}, x_{2n+2}, x_{2n+3})] +$ 

 $\beta_3 D(x_{2n}, x_{2n+1}, x_{2n+2})$ 

*i.e.*  $D(x_{2n+1}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+1}, x_{2n+2}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) + \beta_2 D(x_{2n+1}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+1}, x_{2n+2}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+1}, x_{2n+2}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+1}, x_{2n+2}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+1}, x_{2n+2}) + \beta_2 D(x_{2n}, x_{2n+2}, x_{2n+3}) \le \beta_1 D(x_{2n+1}, x_{2n+2}) \le \beta_1 D(x_{2n+1}, x_{2n+1}) \le \beta_1 D(x_{2n+1}, x_{2n+1}) \le \beta_1 D(x_{2n+1}) \ge \beta_1 D(x_{2n+1}) \ge \beta_1 D(x_{2n+1}) \ge \beta_1 D(x_{2n+1}) \ge \beta_1$ 

$$\beta_3 D(x_{2n}, x_{2n+1}, x_{2n+2})$$

 $i.e.D(x_{2n+1}, x_{2n+2}, x_{2n+3})$ 

 $\leq \beta_1 [D(x_{2n+3}, x_{2n+1}, x_{2n+2}) + D(x_{2n+1}, x_{2n+3}, x_{2n+2}) + D(x_{2n+1}, x_{2n+1}, x_{2n+3})]$  $+ \beta_2 [D(x_{2n+1}, x_{2n+2}, x_{2n+3}) + D(x_{2n}, x_{2n+1}, x_{2n+3}) + D(x_{2n}, x_{2n+2}, x_{2n+1})]$  $+ \beta_3 D(x_{2n}, x_{2n+1}, x_{2n+2})$ 

*i.e.*  $D(x_{2n+1}, x_{2n+2}, x_{2n+3})[1 - 2\beta_1 - \beta_2]$ 

$$\leq [\beta_1 + 2\beta_2 + \beta_3] \max \begin{bmatrix} D(x_{2n+1}, x_{2n+1}, x_{2n+3}), D(x_{2n}, x_{2n+1}, x_{2n+3}) \\ D(x_{2n}, x_{2n+2}, x_{2n+1}), D(x_{2n}, x_{2n+1}, x_{2n+2}) \end{bmatrix}$$

*i.e.*  $D(x_{2n+1}, x_{2n+2}, x_{2n+3})$ 

$$\leq p \max \begin{bmatrix} D(x_{2n+1}, x_{2n+1}, x_{2n+3}), D(x_{2n}, x_{2n+1}, x_{2n+3}) \\ D(x_{2n}, x_{2n+2}, x_{2n+1}), D(x_{2n}, x_{2n+1}, x_{2n+2}) \end{bmatrix}, \text{ here } p = \frac{\beta_1 + 2\beta_2 + \beta_3}{1 - 2\beta_1 - \beta_2}$$

But we have to given that  $3\beta_1 + 3\beta_2 < 1 - \beta_3$  so  $p = \frac{\beta_1 + 2\beta_2 + \beta_3}{1 - 2\beta_1 - \beta_2} < 1$ 

Letting  $q = \max \begin{bmatrix} D(x_{2n+1}, x_{2n+1}, x_{2n+3}), D(x_{2n}, x_{2n+1}, x_{2n+3}) \\ D(x_{2n}, x_{2n+2}, x_{2n+1}), D(x_{2n}, x_{2n+1}, x_{2n+2}) \end{bmatrix}$ . If  $q = D(x_{2n+1}, x_{2n+2}, x_{2n+3})$  then we achieve  $D(x_{2n+1}, x_{2n+2}, x_{2n+3}) \le pD(x_{2n+1}, x_{2n+1}, x_{2n+3})$  and this implies  $D(x_{2n+1}, x_{2n+2}, x_{2n+3}) \le pD(x_{2n}, x_{2n}, x_{2n+3})$  similarly we can obtain  $D(x_{2n+1}, x_{2n+2}, x_{2n+3})$ 

 $< pD(x_{2n}, x_{2n}, x_{2n+2}) < p^2D(x_{2n-1}, x_{2n-1}, x_{2n+2}) < \dots < p^2D(x_1, x_1, x_3)$ . Now when we have  $q = D(x_{2n}, x_{2n+1}, x_{2n+3})$  then we get  $D(x_{2n+1}, x_{2n+2}, x_{2n+3}) \le pD(x_{2n}, x_{2n+1}, x_{2n+3})$  and hence  $D(x_{2n}, x_{2n+1}, x_{2n+2}) \le pD(x_{2n-1}, x_{2n}, x_{2n+2})$ . So by symmetry  $D(x_{2n+1}, x_{2n+2}, x_{2n+3})$ 

 $< pD(x_{2n}, x_{2n+1}, x_{2n+3}) < p^2D(x_{2n-1}, x_{2n}, x_{2n+1}) < \cdots < p^{2n+1}D(x_0, x_1, x_3)$ . Again, we have  $q = D(x_{2n}, x_{2n+2}, x_{2n+1})$  then we get  $D(x_{2n+1}, x_{2n+2}, x_{2n+3}) < p^{2n+1}D(x_0, x_2, x_1)$  and which shows that  $\{x_n\}$  is a Cauchy sequence because p < 1. Hence there exists some point  $u \in X$  such that  $\lim_{n\to\infty} x_n = u$  because X is complete. Now we shall show that u is the common fixed point of  $T_1, T_2$  and  $T_3 D(T_1u, T_2u, T_3x_{2n+3}) = D(T_1u, T_2u, T_3x_{2n+2})$ 

$$\leq \beta_{1} \max[D(u, T_{1}u, T_{2}u), D(u, T_{2}u, T_{3}x_{2n+3}), D(u, T_{3}x_{2n+3}, T_{1}u)] + \beta_{2} \max[D(u, T_{2}u, T_{3}x_{2n+3}), D(u, u, x_{2n+2}), D(u, T_{2}u, T_{3}x_{2n+3})] + \beta_{3}D(u, T_{1}u, T_{2}u) \\\leq \beta_{1} \max[D(u, T_{1}u, T_{2}u), D(u, T_{2}u, x_{2n+3}), D(u, x_{2n+3}, T_{1}u)] + \beta_{2} \max[D(u, T_{2}u, x_{2n+3}), D(u, u, x_{2n+2}), D(u, T_{2}u, T_{3}x_{2n+3})] + \beta_{3}D(u, T_{1}u, T_{2}u)$$

Now, when  $n \to \infty$  we achieve  $D(T_1u, T_2u, u) \le 0$  and this shows that  $T_1u = T_2u = u$  by symmetry we also achieve  $T_2u = T_3u = u$ . Thus,  $T_1u = T_2u = T_3u$ .

**Theorem 2.2** If *T* meets the criteria, let *T* be an orbitally continuous mapping of a bounded complete D-metric space *X* into itself such that

(i)  $x_n \to x, y_n \to y, z_n \to z$  in X then  $D(x_n, y_n, z_n) \to D(x, y, z)$ 

 $(ii) D(Tx,Ty,Tz) \le \alpha_1 D(x,y,Tz) + \alpha_2 \max\{D(x,Ty,Tz), D(y,Tx,Tz)\} +$ 

 $\alpha_{3} \max\{D(x, Ty, Tz), D(y, Tx, Tz)\} + \alpha_{4} \max\{D(Ty, T^{2}x, Tz), D(x, T^{2}x, Tz)\}$ 

 $+\alpha_5 \max\{D(Tx, T^2x, Tz)\}$ 

 $\forall x, y, z \in X$  and  $\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5 \in R$ :  $\alpha_1 + \alpha_2 + 3\alpha_3 < 1 - 3\alpha_4 - \alpha_5$  for each  $x \in X$ , the sequence  $\{T^n x\}$  converges to a fixed point of *T*.

**Proof:** Let  $x_0$  be an arbitrary point of *X*. Now we define a sequence  $\{x_n\}$  by  $x_1 = Tx_0, x_2 = Tx_1, \dots, x_n = Tx_{n-1}$ . If for some  $n \ge 0$ ,  $x_n = x_{n+1}$ , then  $x_n$  is a fixed point of *T*. Now assume that  $x_n \ne x_{n+1} \forall n = 0, 1, 2, \dots$ . From the hypothesis we have *T* satisfies the condition

$$D(Tx, Ty, Tz) \le \alpha_1 D(x, y, Tz) + \alpha_2 \max\{D(x, Ty, Tz), D(y, Tx, Tz)\} + \alpha_3 \max\{D(x, Ty, Tz), D(y, Tx, Tz)\} + \alpha_4 \max\{D(Ty, T^2x, Tz), D(x, T^2x, Tz)\} + \alpha_5 \max\{D(Tx, T^2x, Tz)\}.$$

From the above condition we achieve the result

$$\begin{split} D(Tx_{n-1}, Tx_n, Tx_{n+1}) &\leq \alpha_1 D(x_{n-1}, x_n, x_{n+2}) + \alpha_2 \max\{D(x_{n-1}, x_n, x_{n+2}), D(x_n, x_{n+1}, x_{n+2})\} \\ &+ \alpha_3 \max\{D(x_{n-1}, x_{n+1}, x_{n+2}), D(x_n, x_n, x_{n+2})\} + \\ &\alpha_4 \max\{D(x_{n+1}, x_{n+1}, x_{n+2}), D(x_{n-1}, x_{n+1}, x_{n+2})\} + \alpha_5 \max\{D(x_n, x_{n+1}, x_{n+2})\} \\ \text{or, } D(x_n, x_{n+1}, x_{n+2}) &\leq \alpha_1 D(x_{n-1}, x_n, x_{n+2}) + \alpha_2 D(x_{n-1}, x_n, x_{n+2}) + \alpha_3 D(x_{n-1}, x_n, x_{n+2}) \\ &+ \alpha_4 D(x_{n+1}, x_{n+1}, x_{n+2}) + \alpha_5 D(x_n, x_{n+1}, x_{n+2}) \\ &\leq \alpha_1 D(x_{n-1}, x_n, x_{n+2}) + \alpha_2 D(x_{n-1}, x_n, x_{n+2}) \\ &+ \alpha_3 [D(x_n, x_{n+1}, x_{n+2}) + D(x_{n-1}, x_n, x_{n+2}) + D(x_{n-1}, x_{n+1}, x_n)] \\ &+ \alpha_4 [D(x_n, x_{n+1}, x_{n+2}) + D(x_{n-1}, x_n, x_{n+2}) + D(x_{n+1}, x_{n+1}, x_n)] \\ &+ \alpha_3 D(x_{n-1}, x_{n+1}, x_{n+2}) + D(x_{n-1}, x_n, x_{n+2}) \\ &+ \alpha_3 D(x_{n-1}, x_{n+1}, x_n) + \alpha_4 D(x_{n+1}, x_{n+1}, x_n) \\ &\leq [\alpha_1 + \alpha_2 + 2\alpha_3 + \alpha_4] \max[D(x_{n-1}, x_n, x_{n+2}), D(x_{n-1}, x_{n+1}, x_n), D(x_{n+1}, x_{n+1}, x_n)] \\ &i.e. D(x_n, x_{n+1}, x_{n+2}) \leq p \max[D(x_{n-1}, x_n, x_{n+2}), D(x_{n-1}, x_{n+1}, x_n), D(x_{n+1}, x_{n+1}, x_n)] \end{split}$$

Here  $p = \frac{\alpha_1 + \alpha_2 + 2\alpha_3 + \alpha_4}{1 - \alpha_3 - 2\alpha_4 - \alpha_5} < 1$  due to  $\alpha_1 + \alpha_2 + 3\alpha_3 < 1 - 3\alpha_4 - \alpha_5$ 

*i. e.*  $D(x_n, x_{n+1}, x_{n+2}) \le pD(x_{n-1}, x_n, x_{n+2}), D(x_n, x_{n+1}, x_{n+2}) \le pD(x_{n-1}, x_{n+1}, x_n)$  and also

 $\begin{array}{l} D(x_n, x_{n+1}, x_{n+2}) \leq pD(x_{n+1}, x_{n+1}, x_n) \quad i.e. \quad D(x_n, x_{n+1}, x_{n+2}) \leq p^n D(x_0, x_1, x_3) \quad \text{similarly we achieve } D(x_n, x_{n+1}, x_{n+2}) \leq p^n D(x_0, x_2, x_1) \quad \text{This concludes the result that } D(x_n, x_{n+1}, x_{n+2}) \leq p^n D(x_2, x_2, x_1). \quad \text{This concludes the result that } D(x_n, x_{n+1}, x_{n+2}) \leq p^n \max[D(x_0, x_1, x_3), D(x_0, x_2, x_1), D(x_2, x_2, x_1)] \text{ and hence } \{x_n\} \text{ is a Cauchy sequence because } p < 1. \text{ On the other hand } X \text{ is complete. So } \{x_n\} \text{ converges to a point } q \in X. \text{ This implies that } \lim_{n \to \infty} D(T^{n+1}x_0, Tq, r) = 0. \text{ But } T \text{ is orbitally continuous } D(q, Tq, r) \leq D(q, Tq, T^{n+1}x_0) + D(q, T^{n+1}x_0, r) + D(T^{n+1}x_0, Tq, r) \text{ approaches to } 0 \text{ as } n \to \infty. \text{ Which leads us } d(q, Tq, r) = 0 \text{ but } q \neq Tq. \text{ Also } D(q, Tq, r) \neq 0 \text{ for any } r. \text{ Hence } q = Tq. \text{ Hene } q \text{ is a fixed point of } T. \end{array}$ 

**Corollary 2.3** If *X* be a complete D-metric space and  $T_1$  and  $T_2$  be self-mapping on *X* satisfy the criterion  $\Delta_d \left( O_{T_1}(T_2x_0) \right) < \infty$ ,  $T_1(X) \subseteq T_2(X)$ , the pair  $(T_1, T_2)$  is D-compatible and  $T_2$  is continuous, and for some  $k \in [0, 1) \forall u, v, w \in X$ ,



 $D(T_1u, T_1v, T_1w) \le k \max \begin{bmatrix} D(T_2u, T_2v, T_2w), D(T_1u, T_2u, T_2w), D(T_1y, T_2v, T_2w) \\ D(T_1u, T_2v, T_2w), D(T_1v, T_2u, T_2w) \end{bmatrix}$ . Consequently,  $T_1$  and  $T_2$  share a unique common fixed point.

#### REFERENCES

**1. Dhage, B. C. (1992):** Generalized metric spaces and mapping with fixed points, Bull. Cal. Math. Soc., 84, 329-336.

2. Dhage, B. C. (1999): A common fixed point principle in D-metric space, Bull. Cal. Math. Soc., 91, 475-480.

3. Dhage, B. C. (1999): Some results on common fixed point I, Indian J. Pure Appl. Math., 30 (1999), 827-837.

**4. Rhoades, B. E. (1996):** A fixed point theorem for generalized metric space, International J. Math. and Math. Sci., 19, 457-460.

**5.** Singh, B. et al. (2005): Semi-compatibility and fixed point theorems in an unbounded D-metric space, International J. Math. and Math. Sci., 5, 789-801.

**6.** Ume, J. S., Kim, J. K. (2000): Common Fixed Point Theorems in D-Metric Spaces with Local Boundedness. Indian Journal of Pure Appl. Math. 31, 865-871.

**7. Veerapandi, T., Chandrasekhara Rao, K. (1995):** Fixed Point Theorems of Some Multivalued Mappings in a D-Metric Space. Bull. Cal. Math. Soc. 87, 549-556.

### **Biography of author**



Dr. Rohit Kumar Verma, Associate Professor & HOD, Department of Mathematics, Bharti Vishwavidyalaya, Durg, C.G., India.

He is a well known author in the field of the journal scope. He obtained his highest degree from RSU, Raipur (C.G.) and worked in engineering institution for over a decade. Currently he is working in a capacity of Associate Professor and HOD, Department of Mathematics, Bharti Vishwavidyalaya, Durg (C.G.). In addition to 30 original research publications in the best journals, he also published two research book by LAP in 2013 and 2023 in the areas of information theory and channel capacity that fascinate him. He is the Chairperson, the Board of Studies Department of Mathematics at Bharti Vishwavidyalaya in Durg, C.G., India. He has published two patents in a variety of fields of research. In addition to numerous other international journals, he reviews for the American Journal of Applied Mathematics (AJAM). In addition to the Indian Mathematical Society, he is a member of the Indian Society for Technical Education (ISTE) (IMS).