

Improving Voltage Profile in Distribution Systems using Custom Power Devices (CPD)

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Abstract - This paper reports Matlab Simulink test results obtained on different radial distribution systems with and without DVR. At the customer end, maintaining good voltage profile is prominent. Power quality problems decreases the efficiency of the distribution system and makes unhealthy relations between the customer and sending end. Power quality problems such as voltage sag and poor voltage profile are the important problems to control and mitigate so that user equipment works healthily. In this paper, custom power devices (CPD) are proposed for mitigating these power quality problems. Dynamic voltage restorer (DVR) and distribution static compensator (D-STATCOM) are the two examples custom power device that serves the purpose of voltage sag or swell mitigation. These devices which enhance the voltage stability in the system without effecting the normal operation of the system even at the fault conditions in the distribution system. In the sense, it maintains the quality of power by its deliberate action of operation with respective to the voltage sag or voltage swell and improve the voltage profile. DVR is accomplished with Vector control technique for its control for IEEE 11 bus 33 bus and 69 bus radial distribution system in this paper.

Key Words: Custom power devices (CPD), Dynamic voltage restorer (DVR), vector control technique.

1. INTRODUCTION

With the increase of more sensitive and non-linear loads day by day, there is demand for the production. Along with the production and supply in the power system the power quality is the important aspect that is to be considered. Power quality is the term that can be defined as a set of electrical boundaries that can be considered or allowed for an equipment to function in its intended manner without significant loss of performance or life expectancy. Power quality problems like voltage sag, voltage swell, voltage fluctuations, etc., are frequent in the system [6]. For obtaining good power quality, power quality problems are to be controlled.

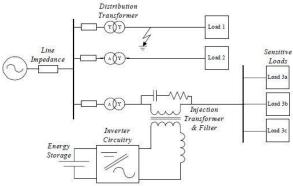
Here the custom power devices (CPD) are placed at the point of common coupling or also at the bus where there is lesser voltage than it is intended to be. In this

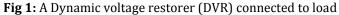
paper mitigating voltage sag and boosting the dropped voltage in to the buses by custom power devices (CPD) using vector control technique is modelled for IEEE 11 bus, 33 bus and 69 bus radial distribution system. Vector control technique is the simplest control technique. The proposed systems are modelled in MATLAB software and the results were discussed about the operation of custom power devices (CPD) for IEEE 11 bus, 33 bus and 69 bus radial distribution system that helped in improving the voltage profile in the system.

2. CUSTOM POWER DEVICES (CPD):

A DVR consists of a voltage source converter (VSC) [3]-[10]. A DVR is primarily for use at the distribution level. The basic principle is to inject a voltage in series with the line. DC power bank or a battery system and a booster or injection transformer connected along with the distribution line in series so as to induce or compensates for the lower voltage on the distribution bus bar [9]. From the Fig.1, the operation of DVR mitigating the voltage sag is observed [3].

The Distribution Static Compensator (D-STATCOM) induces variable shunt compensation when there is voltage fluctuation in the system. An ideal application of D-STATCOM is to prevent disturbing loads from polluting the rest of the distribution system.





3. WORKING PRINCIPLE OF DVR:

In the distribution system the significant deviations from the nominal voltage are the problems for sensitive appliances. The interruptions are the worst cases that occur when faults occur in the supply. The supply voltage is V_S and load voltage is V_L , dynamically controlled voltage V_{DVR} is generated by the converter which is in series with the line voltage. This is induced using the booster transformer. The hysteresis voltage control which operates and controls the VSC with the triggering pulses [7], [8].

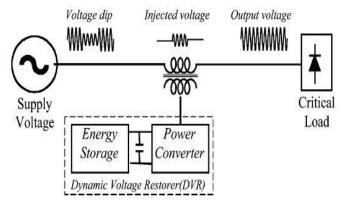


Fig 2: Schematic diagram of DVR

4. OPERATING MODES OF A DVR:

DVR has three modes of operations. The operation modes are protection mode, standby mode and boost mode. In the case of protection mode, if there is an occurrence of fault which DVR cannot operate and with stand then DVR turns to protection with the isolation switch which is connected with the line. If there is no fault or voltage drop in the system then DVR start to act in the standby mode. At this moment V_{DVR} is zero. The booster transformer does not inject voltage in to the line at this mode. As there is no sag condition in the line. Most of the time DVR will be in this standby mode only. In the boost mode, V_{DVR} is greater than zero. When the drop in supply voltage is observed, DVR comes in to operation dynamically and boosts up the drop voltage in to the line [5].

5. VECTOR CONTROL TECHNIQUE:

Different voltage injection methods are associated with the operation of custom power devices (CPD) with the distribution system. Some of the methods are [2]-[4] Monitoring peak values of supply voltage, Phase locked-loop (PLL) for each phase, Monitoring of V_d in a vector controller, Fourier Transform, Wavelet Transformer method to each phase.

Fig.3 represents the Simulink model of control technique and generating of the triggering pulses that are used to operate and control the voltage source converter (VSC) [9]. The control technique that is

developed is implemented to control distribution system voltage with the injected voltage by the DVR. The control technique that is used is voltage vector control with decoupling approach. The custom power devices (CPD) have the ability of voltage sag/swell compensation to effectively protect sensitive loads at the customer end. This depends on the time required by the detection strategy along with the time required to inject the voltage. The detection scheme is an algorithm which extracts amplitude, phase and angle status data from point of common coupling or at the customer end voltages. The angle theta of the utility is observer by implementing three phase Phase-Locked Loop (PLL) method. This data is imported to an algorithm for detection and reference generation, as represented in Fig. 3. By comparing these voltages of reference with the system voltage the obtained command signal is generated using PWM technique and is used to trigger the VSC in order to generate the required compensating voltage that is to be induced in the system using the custom power devices (CPD).

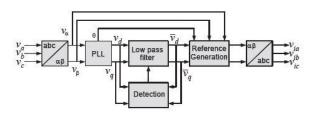
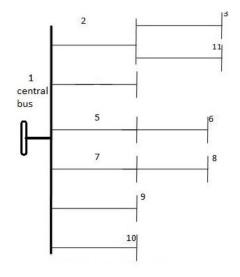
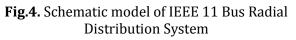


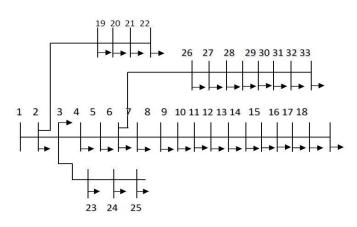
Fig 3: Reference generation and detection model

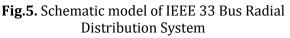
6. TEST SYSTEM:

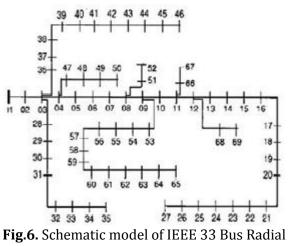
A test system is modelled for DVR implementation. The standard system data for IEEE 11 Bus Radial Distribution System, IEEE 33 Bus Radial Distribution and IEEE 69 Bus Radial Distribution System is considered. Single line diagram of these systems using the custom power devices (CPD) are represented in the fig.4, fig. 5 and fig. 6 respectively. These are modelled according to standard IEEE representation. Results that are represented in the below section gives a clear analysis of improvement in voltage profile by mitigating voltage sag using custom power devices (CPD) which is controlled and operated by the vector control technique. Due to load variations in the distribution system the voltages at the buses changes. In order to improve the voltage profile at buses, a DVR is employed at the location where DVR can operate optimally. The results thus obtained with the Simulink models proves that DVR is efficient in mitigating Voltage sag than compared to D-STATCOM.











Distribution System

7. RESULTS:

Case-I: IEEE 11 Bus Radial Distribution System:

The Fig.7 gives the comparison of Voltage response of IEEE 11 Bus Radial Distribution System without and with the custom power devices (CPD). The number of buses i.e. Bus 1 to bus 11 are plotted in the x axis and the voltage values in per units (pu) are represented in another axis. The improvement in the voltage can be seen in Fig.7.

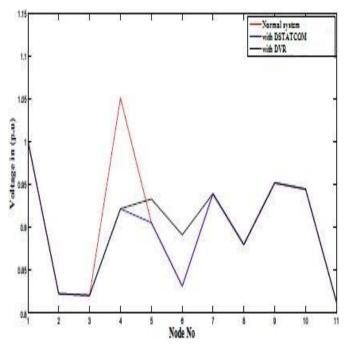


Fig.7.Comparision of Voltage response of IEEE 11 Bus Radial Distribution System without and with the custom power devices (CPD)

Case-II: IEEE 33 Bus Radial Distribution System:

The Fig.8 gives the comparison of Voltage response of IEEE 11 Bus Radial Distribution System without and with the custom power devices (CPD). The number of buses i.e. Bus 1 to bus 33 are plotted in the x axis and the voltage values in per units (pu) are represented in another axis. The improvement in the voltage is in Fig.8.

Comparison of Voltage Profiles of IEEE-11 Bus Radial Distribution System, IEEE-33 Bus Radial Distribution System and IEEE-69 Bus Radial Distribution System using CPD:

IEEE 1	IEEE 11Bus Radial Distribution System			IEEE 33 Bus Radial Distribution System			IEEE 69 Bus Radial Distribution System		
Bus	Normal	With	With	Normal	With	With	Normal	With	With
No.	Voltage	DSTATCOM	DVR	Voltage	DSTAT COM	DVR	Voltage	DSTATCOM	DVR
1	0.9095	0.9111	0.9185	0.9967	0.9969	0.9969	1	1	1
2	0.9025	0.9041	0.9114	0.9942	0.9944	0.9945	1	1	1
3	0.9024	0.9040	0.9113	0.9810	0.9812	0.9816	0.9999	0.9999	0.9999
4	0.9057	0.9073	0.9146	0.9724	0.9727	0.9728	0.9999	0.9999	0.9999
5	0.9055	0.9070	0.9144	0.9653	0.9655	0.9655	0.9993	0.9993	0.9997
6	0.9025	0.9040	0.9114	0.9492	0.9497	0.9497	0.995	0.9965	0.9959
7	0.9068	0.9084	0.9157	0.9172	1.0101	1.0118	0.9875	0.9875	0.9895
8	0.9041	0.9057	0.9130	0.9964	1.0051	1.0071	0.9861	0.9861	0.9891
9	0.8932	0.8948	0.9158	0.9599	0.9983	0.9983	0.9854	0.9854	0.9873
10	0.8925	0.8941	0.9151	0.9550	0.9933	0.9966	0.9804	0.9804	0.9884
11	0.9021	0.9037	0.9110	0.9543	0.9925	0.9955	0.9794	0.9794	0.9794
12 13		+		0.9540 0.9490	0.9922 0.9870	0.9946	0.9762 0.9733	0.9762 0.9733	0.9784 0.9776
13		+		0.9490	0.9870	0.9895	0.9733	0.9733	0.97767
14		1		0.9471	0.9850	0.9876	0.9704	0.9704	0.9767
16				0.9437	0.9833	0.9875	0.9670	0.9671	0.9694
17				0.9436	0.9814	0.9854	0.9662	0.9662	0.9686
18		1		0.9433	0.9811	0.9841	0.9662	0.9662	0.9692
19		1		0.9805	0.9807	0.9837	0.9657	0.9657	0.9687
20				0.9770	0.9772	0.9752	0.9654	0.9654	0.9684
21				0.9763	0.9765	0.9765	0.965	0.965	0.9676
22				0.9757	0.9759	0.9749	0.965	0.965	0.9676
23				0.9702	0.9705	0.9725	0.9649	0.9649	0.9679
24				0.9664	0.9666	0.9648	0.9647	0.9647	0.9687
25				0.9633	0.9635	0.9658	0.9644	0.9644	0.9646
26				0.9472	0.9477	0.9477	0.9645	0.9645	0.9666
27				0.9453	0.9458	0.9458	0.9645	0.9645	0.9685
28				0.9377	0.9382	0.9375	0.9999	0.9999	0.9999
29				0.9323	0.9328	0.9386	0.9999	0.9999	0.9999
30				0.9295	0.9300	0.9345	0.9997	0.9997	0.9997
31				0.9243	0.9248	0.9248	0.9996	0.9996	0.9996
32				0.9231	0.9236	0.9247	0.9994	0.9994	0.9994
33		-		0.9221	0.9226	0.9256	0.9990	0.9990	0.9990
34							0.9990	0.9990	0.9990
35							0.9999 0.9998	0.9999	0.9999
36 37		-		-			0.9998	0.9998	0.9996
38							0.9996	0.9996	0.9996
39							0.9996	0.9996	0.9996
40							0.9996	0.9996	0.9996
41							0.9989	0.9989	0.9989
42		1					0.9986	0.9986	0.9986
43	1		1	1	1	1	0.9985	0.9985	0.9985
44							0.9985	0.9985	0.9985
45						1	0.9984	0.9984	0.9984
46							0.9984	0.9984	0.9984
47							0.9998	0.9998	0.9998
48							0.9986	0.9986	0.9986
49							0.9947	0.9947	0.9967
50							0.9942	0.9942	0.9972
51							0.9861	0.9861	0.9871
52							0.9861	0.9861	0.9861
53							0.9841	0.9841	0.9867
54							0.9826	0.9826	0.9848
55					-	ļ	0.9806	0.9806	0.9836
56				-	-	ļ	0.9787	0.9787	0.9782
57							0.9699	0.9699	0.9699
				1					0.965
58 59							0.9656	0.9656	

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60				0.9623	0.9623	0.9623
61				0.9593	0.9593	0.9593
62				0.9598	0.9598	0.9598
63				0.9606	0.9606	0.9626
64				0.9588	0.9588	0.9588
65				0.983	0.983	0.983
66				0.9793	0.9793	0.9793
67				0.9793	0.9793	0.9793
68				0.9759	0.9759	0.9770
69				0.9763	0.9801	0.9815

Table.1 Comparison of Voltage Profiles of both systems at each bus

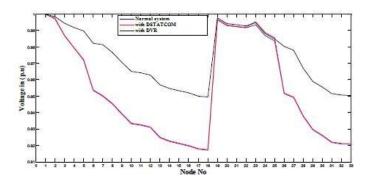
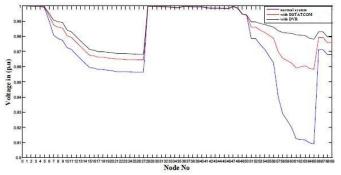


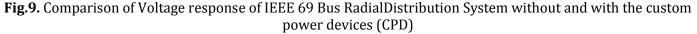
Fig.8. Comparison of Voltage response of IEEE 33 Bus Radial Distribution System without and with the custom power devices (CPD)

Here the custom power devices (CPD) is placed at bus 9 for 11 bus system and at the bus 7 for 33 bus system in order to get good voltage profile in the corresponding buses.

Case-III: IEEE 69 Bus Radial Distribution System:

The Fig.9 gives the comparison of Voltage response of IEEE 69 Bus Radial Distribution System without and with the custom power devices (CPD). The number of buses i.e. Bus 1 to bus 69 are plotted in the x axis and the voltage values in per units (pu) are represented in another axis. The improvement in the voltage can be seen in Fig.9.





Hence it can be said as an optimal location for the placement of DVR in the system because by placing DVR better voltage profile at every bus in the concern system is obtained than placing the DVR at other bus locations. From the obtained results tabulated in the next section validates the above discussed statement.

8. CONCLUSION:

The proposed model of Dynamic voltage restorer (DVR) which is controlled and operated by Vector control technique is modelled using MATLAB Simulink. In this paper an efficient method is used for improving the voltage

profile of radial distribution system. The DVR is implemented for the test cases. Vector Control technique simplifies the objective of DVR compared to other conventional methods by dynamically inducing the required voltage. The following conclusions are drawn from the modeling of Without DVR with DVR system and their comparison of Voltage values. From the results obtained and from the tabulated values of voltage profile at each bus for the three cases (11 bus, 33 bus and 69 bus) in table.1 it can be concluded that by placing DVR at optimum location, significant improvement in voltage profile can be achieved. Introducing DVR improves voltage profile and reduces voltage sag. The above tables for the practical values of IEEE 11-bus, 33-bus and 69 bus proved this statement.

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