

Design and development of manually operated fertiliser spreader

Chetan Chaudhari¹, Vishwajeet Gaikwad², Amol Bhavake³, Ashwin Bawale⁴

^{1,2,3,4}Bachelor's student, Dept. of Mechanical Engineering, RMD Sinhgad School of Engineering, Pune, India

Abstract - In order to provide a better alternative to traditional and traditional (scattering by hand) methods for dispersion of fertiliser a manually operated fertiliser spreader is designed and developed. Objective of the equipment is to uniformly disperse fertiliser in farm. Bearing in mind the fact that this equipment is manually operated, ergonomics has been a major factor hence, it is evident to keep the equipment light in weight. The human pushing force is converted into rotational motion of wheel and with aptly designed gearbox unit this motion is further transmitted to impeller disc. This fertiliser spreading equipment works on the principle of centrifugal force, wherein the fertiliser is poured from hopper on the impeller disc which rotates with proportionate speed with that of wheels so that fertiliser is dispersed in a specified range uniformly.

Key Words: Rotational motion, Centrifugal force, Gearbox unit, Hopper, Human pushing force

1. INTRODUCTION

India is an agricultural country, almost 70% people live in rural areas and 90% of their income is generated from agriculture. Indian economy is heavily dependent on agriculture and contributes about 30% to GNP. Over the years, agriculture has witnessed tremendous changes in methods seed plantation, irrigation, pesticides and modes utilised for its dispersion. Although, a great deal of research and engineering advancements have been made on spray pesticides, granular pesticides and fertilisers lack innovative methods of dispersion [1][2]. Dispersion of fertilisers in traditional way is quite time consuming, expensive and strenuous. Despite the fact, some tractor operated equipment for fertiliser spreading are available, it is viable to look for cheaper alternatives considering financial situation of majority Indian farmers. So, designing a manually operated machine for spreading fertiliser would most certainly help the majority group.

2. MATERIAL SELECTION

Table -1: Selected material for components

| Components | Material | Ultimate Tensile Strength (N/mm ²) | Yield Strength (N/mm ²) |
|---------------|--------------------|--|-------------------------------------|
| Frame | AISI 1018 | 440 | 370 |
| Shaft | AISI 4140 | 800-1100 | 550-700 |
| Gears | AISI 4340 | 850-1550 | 650-1200 |
| Impeller disc | Polyvinyl chloride | 52 | 40 |
| Hopper | Polyethylene | 52 | 42 |

3. FERTILISER FLOW CALCULATIONS

1. Average person can apply 225 N of pushing force [3][4]
2. Walking speed (V_t) of average human being is 0.7 m/s on rough terrain.

Tyre size $d_t = 520\text{mm}$

$$V_t = \pi \cdot d_t \cdot N_t / (60 \cdot 10^3)$$

$$N_t = 25.72 \text{ rpm}$$

$$\text{Impeller disc diameter } (D_i) = 190.5\text{-}228.6 \text{ mm}$$

$$\text{Track width} = 350 \text{ mm}$$

$$\text{Gear Ratio} = 1:4.5$$

$$\text{Speed of Impeller} = \text{Speed of Wheels} / \text{Gear Ratio}$$

$$N_i = 115.74 \text{ rpm}$$

Considering 90% efficiency of the gear box, Speed of impeller is,

$$N_i = 115.74 \cdot 0.9 = 104.166 \text{ rpm}$$

$$\omega = 2\pi N_i / 60$$

$$\omega = 10.908 \text{ rad/s}$$

$$\text{Velocity of fertilizer while leaving impeller: } V = r \cdot \omega$$

$$1.) \text{ For } D_i = 190.5 \text{ mm, } V = 1.038 \text{ m/s}$$

$$2.) \text{ For } D_i = 228.6 \text{ mm, } V = 1.247 \text{ m/s}$$

Maximum Displacement of Fertilizer (X) with height of impeller disc (Y)

$$Y = X \cdot \tan\theta + g \cdot X^2 / (2 \cdot V_i^2 \cdot (\cos\theta)^2)$$

$$\text{As } \theta = 0^\circ$$

$$Y = g \cdot X^2 / (2 \cdot V_i^2)$$

Table - 2: Iterations for displacement of fertilizer with variation in impeller height for $r = 95.25 \text{ mm}$ $V = 1.038 \text{ m/s}$

| Sr. No. | Y (m) | X (m) |
|---------|-------|-------|
| 1 | 0.55 | 0.347 |
| 2 | 0.50 | 0.331 |
| 3 | 0.45 | 0.314 |
| 4 | 0.40 | 0.296 |

Table – 3: Iterations for displacement of fertilizer with variation in impeller height $r = 114.3 \text{ mm}$ $V = 1.247 \text{ m/s}$

| Sr. No. | Y (m) | X (m) |
|---------|-------|-------|
| 1 | 0.55 | 0.417 |
| 2 | 0.50 | 0.398 |
| 3 | 0.45 | 0.377 |
| 4 | 0.40 | 0.356 |

Diameter of Impeller (d) = 190.5 mm to 228.6 mm

Displacement (X) range = 300 to 400 mm

4. HOPPER DESIGN

For Fertilizer: Density (ρ) varies between 900 kg/m^3 to 1600 kg/m^3

Assuming (ρ) = 1400 kg/m^3 (for all types of dry fertilizers)

Diameter of Hopper (d_h) = 228 mm (Maximum)

Length of Hopper (l) = 250 mm

Total mass of fertiliser in Hopper,

$$M = \rho * \text{volume}$$

$$= 11\text{kg}$$

5. FRAME DESIGN

Table – 4: Specifications of frame

| Parameters | Dimensions |
|--------------------|--------------------|
| Hollow Square Pipe | 25 mm*25 mm*1.6 mm |
| Height of Frame | 950 mm |
| Length of Frame | 1110 mm |

Forces on Frame: [7]

1. Weight of frame
2. Human Pushing force
3. Support reaction of bearings on shafts

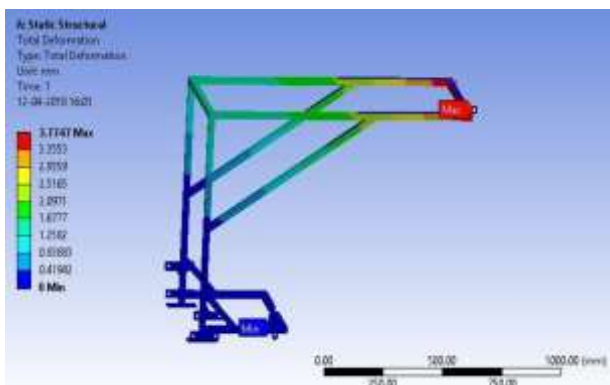


Fig – 1: Static structural analysis showing total deformation of frame

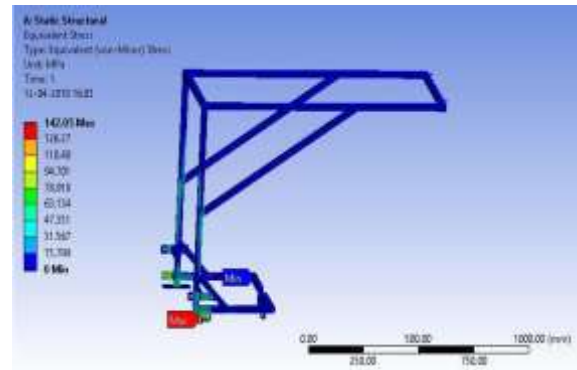


Fig – 2: Static structural analysis showing equivalent stress on frame

6. GEARBOX DESIGN

Required Traction: $F = \mu * M * g$

$$= 275 \text{ N}$$

Torque required: $T = F * (d_t / 2)$

$$= 71.5 \text{ N-m}$$

We need a gearbox which increases the speed from shaft to impeller disc i.e. Overdrive is needed hence gear is driver and pinion is driven member.

Design of Two Stage Gearbox First Stage is bevel gear pair and Second Stage is spur gear pair [5][6]. The required gear ratio is 1:4.5 So, for the first stage Gear ratio i_1 is 1:1.6 and second stage gear ratio i_2 is 1: 2.86.

Hence the resulting gear ratio (G) = $i_1 * i_2 = 1:4.56$.

Table – 5: Specifications of gearbox

| Parameters | First Stage | Second Stage |
|--------------------|-------------|--------------|
| Gear Used | Bevel | Spur |
| Gear Ratio | 1.6 | 2.86 |
| Module | 3.5 mm | 2 mm |
| Teeth on Gear | 16 | 40 |
| Teeth on Pinion | 10 | 14 |
| Diameter of Gear | 56 mm | 80 mm |
| Diameter of Pinion | 35 mm | 28 mm |

7. SHAFT DESIGN

Table – 6: Specifications of Shafts

| Parameters | Dimension |
|--------------------------------|-----------|
| Diameter of wheel shaft | 20 mm |
| Length of wheel shaft | 620 mm |
| Diameter of intermediate shaft | 20 mm |
| Length of intermediate shaft | 80 mm |
| Diameter of impeller shaft | 20 mm |
| Length of impeller shaft | 90 mm |

8. BEARING SELECTION

Table - 7: Bearings for various shafts

| Shaft | Bearing Number |
|--------------|----------------|
| Wheel | 6204 |
| Intermediate | 6204 ETN9 |
| Impeller | 6204 |

9. MODEL

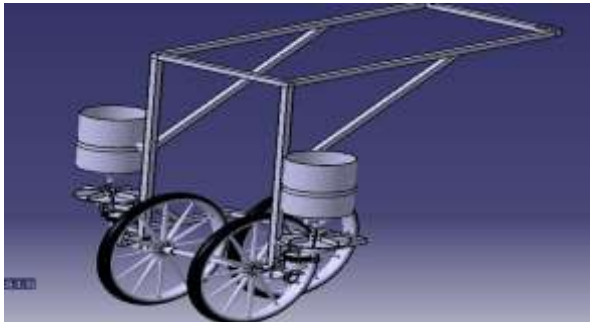


Fig - 3: CATIA model of equipment

10. TESTING

For testing the equipment's working and flow efficiency a simple technique is opted. The important parameters which are tested:

- 1) Mass flow rate and fertilizer from ball valve.
- 2) Displacement of fertilizer from tip and impeller.

Procedure is as follows:

- 1) Mass flow rate of fertilizer is calculated at 60, 75 and 90 degrees of ball valve.
- 2) The velocity of operator as considered is ranging from 0.7 to 1 m/s respectively.
- 3) For each angle of ball valve that are 60, 75 and 90 degrees each variation in equipment velocity of 0.7 m/s, 0.85 m/s and 1m/s displacement of fertilizer from impeller tip is measured.
- 4) This procedure is followed for next angles and displacement readings are noted.

Table - 8: Mass flow rate for various ball valve angles

| Angle (Degree) | Mass of fertiliser (kg) | Average mass | Time (sec) | Mass flow rate of fertiliser (kg/sec) |
|----------------|-------------------------|--------------|------------|---------------------------------------|
| 60 | 0.499 | 0.5046 | 15 | 0.0336 |
| | 0.504 | | | |
| | 0.511 | | | |

| | | | | |
|----|-------|--------|----|--------|
| 75 | 0.840 | 0.8473 | 15 | 0.0565 |
| | 0.847 | | | |
| | 0.855 | | | |
| 90 | 1.295 | 1.2853 | 15 | 0.0857 |
| | 1.276 | | | |
| | 1.285 | | | |

Table - 9: Displacement of fertilizer for valve angle 60° at height of impeller from ground (Y) = 0.45 m

| Velocity (meter/second) | X=Displacement of Fertiliser from impeller (m) | Average Displacement (m) |
|-------------------------|--|--------------------------|
| 0.7 | 0.304 | 0.313 |
| | 0.325 | |
| | 0.312 | |
| 0.85 | 0.350 | 0.362 |
| | 0.374 | |
| | 0.362 | |
| 1 | 0.393 | 0.402 |
| | 0.401 | |
| | 0.412 | |

Table - 10: Displacement of fertilizer for valve angle 75° at height of impeller from ground (Y) = 0.45 m

| Velocity (meter/second) | X=Displacement of Fertiliser from impeller (m) | Average Displacement(m) |
|-------------------------|--|-------------------------|
| 0.7 | 0.436 | 0.427 |
| | 0.401 | |
| | 0.443 | |
| 0.85 | 0.466 | 0.480 |
| | 0.481 | |
| | 0.493 | |
| 1 | 0.517 | 0.516 |
| | 0.531 | |
| | 0.501 | |

Table - 11: Displacement of fertilizer for valve angle 90° at height of impeller from ground (Y) = 0.45 m

| Velocity (meter/second) | X=Displacement of Fertiliser from impeller (m) | Average Distance (X) |
|-------------------------|--|----------------------|
| 0.7 | 0.491 | 0.496 |
| | 0.48 | |
| | 0.517 | |
| 0.85 | 0.587 | 0.598 |
| | 0.610 | |
| | 0.598 | |

| | | |
|---|-------|-------|
| 1 | 0.61 | 0.635 |
| | 0.641 | |
| | 0.653 | |

11. VALIDATION

Table - 12: Comparison of theoretical and practical displacement of fertilizer from impeller

| Velocity | Observed displacement of fertiliser from impeller (m) for various valve angles | | | Theoretical displacement of fertiliser from impeller (m) |
|----------|--|-------|-------|--|
| | 60° | 75° | 90° | |
| 0.7 | 0.313 | 0.362 | 0.402 | 0.362 |
| 0.85 | 0.422 | 0.480 | 0.516 | 0.403 |
| 1 | 0.496 | 0.598 | 0.635 | 0.4324 |

Hence it is observed that:

1. Required displacement of fertilizer 0.362 m to 0.4324 m for velocity range 0.7 m/sec to 1m/sec is obtained by valve position between 63° to 67° angle.

2. Displacement of fertilizer from impeller increases with increase in velocity of equipment. 3. Mass flow rate of fertilizer is increases with increase in valve opening angle.

12. CONCLUSION

Displacement of fertilizer from impeller increases with increase in velocity of equipment. Required displacement of fertilizer 0.362 m to 0.4324 m for velocity range 0.7 m/sec to 1m/sec is obtained by valve position between 63.0° to 67.0° angle. Mass flow rate of fertilizer is easily controlled by valve mechanism which increases from 0.0336 kg/sec to 0.0857 kg/sec with 60° to 90° valve opening angle. This arrangement is useful for crops where distance between two crop rows is more than 2.3 meter.

REFERENCES

- [1] Vignesh.B and Sethuraman.N “Design And fabrication Of Automatic Fertilizer”, International journal for scientific research and development, ISSN:2321-0613, Volume 5, Issue 04, 2017.
- [2] Shailesh Chaudhari, Mansuri Naeem, Prajapati Jigar and Prajapati Prayesh “Design and Development of Fertilizer Spreader Machine”, International Journal of Engineering science and technology, ISSN:2277-9655, April 2017.
- [3] Waldemar Karwowski, William Marras, “Occupational Ergonomics”, Chapter 23 Push Pull Force Limits.
- [4] Reza Shadmehr, Ferdinando A. Mussa-Ivaldi, and Emilio Bizzi, “Postural Force Fields of the Human Arm and

Their Role in Generating Multi joint Movements”, Journal of neuroscience, January 1993, p.p. 45-82.

- [5] R. S. Khurmi, J. K. Gupta, “Machine Design”, S. Chand Publications New Delhi,1st edition,2010 p.p. 387-390, 510-512, 766-774.
- [6] V. B. Bhandari “Design of Machine Elements”, Tata McGraw Hill Publication, Third Edition 2010, p.p.330-348, 711-727.
- [7] S. S. Rattan “Strength of Materials”, Tata McGraw Hill Publication, “Shear Force and Bending Moment”, Chapter 4, Third Edition 2017, p.p. 153-195, 198-276, 317-396