

A Novel Gabor Feed Forward Network for Pose Invariant Face Recognition

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Abstract - Gabor magnitude is known to be among the most classifications representations for face images due to emphasis co-localization property. However, such things would have on adverse effects even when the images are captured under moderate head pose change. To address this pose compassion issue as well as other conservative imaging distinctions, we propose an analytic Gabor feed forward network which can rivet such moderate changes. Necessarily, the network works swallow on the raw face images and produces directionally projected Gabor magnitude features at the hidden layer. Subsequently, numerous sets of magnitude features found from various alignments and scales are fused at the output layer for final classification decision. The network model is rationally trained using a single sample per identity. The acquired solution is worldwide optimal with respect to the classification total error rate. Our observed experiments conducted on five face datasets (six subsets) from the public domain show positive results in terms of identification precision and computational proficiency.

Key Words: Face Recognition across Pose, Single Hidden Layer Feed forward Network, Gabor Filtering, Information Fusion

1. INTRODUCTION

Face recognition (FR) in a very simple term, is a process of identifying the face of a person by a system. Conversely, identifying faces through a digital eve is not an easy enthusiast to crack. Whenever face recognition is used across the surveillance system it is often very difficult to obtain the faces in measured environment. So there has to be a system which is accomplished of identifying the faces captured even in poor lightning circumstances and variations in poses as against the faces taken in controlled environment. Even though many approaches have been proposed during last decade; however, real-world situations remain a challenge. Additionally, all the methods are greatly affected by variations and their performance get ruined when variations in both pose and illumination are present. The illumination problem arise when the same face appears differently due to the change in lighting and pose variation comes from the fact when there exists head rotation. During the last decade, the

major approaches towards the face recognition system that have been proposed can be classified into four main categories

1. All-inclusive method, which uses whole face region; 2. Model based methods which employ shape and consistency of the face, along with 3D depth information; 3. Template based face recognition, where face templates are extracted and used for recognition; and 4. Techniques using Neural Networks. If all the approaches of four categories recorded above are taken into considered, many problems have been solved; but still so many of them endure in this field of research. In this paper, we provide a summary of all the important illumination and pose approaches which are widely used throughout the world for illumination and pose problem. We discovered the methods of implementation of each approach and on the basis of this examination, we are presenting a survey paper that embraces as much literature study for the reader to understand that what exactly the variations are that can be caused by variation in illumination and pose, what approaches had been taken up till now to make continuous improvements in existing systems and their drawbacks etc. We also provide a inclusive review on classifiers that have been positively used in face recognition system.

2. LITERATURE REVIEW

In this section, we provide the contextual information of two methods, namely the two-dimensional Gabor filtering for image representation and the total error rate minimization for multi-category organization, for instantaneous reference.

A. Two-dimensional (2D) Gabor filtering method

Let $z = [c,r]^T$ denote a pixel coordinate, where *T* indicates the vector/matrix transposition, and suppose $j = \sqrt{-1}$. According to a Gabor kernel is defined as follows:

$$\Psi_{\mu,\nu}(\mathbf{z} - \frac{\mu,\nu}{\sigma^2} e^{-\frac{\|\mathbf{k}_{\mu,\nu}\|^2}{2\sigma^2}} \times \left[e^{j\mathbf{k}_{\mu,\nu}^T \mathbf{z}} - e^{-\frac{\sigma^2}{2}} \right], \quad (1)^{\|\mathbf{k}_{\mu,\nu}\|} \mathbf{k} = \mathbf{z}$$

where $\Psi\mu\nu(z)\in C$ is a complex Gabor division obtained using alignment μ and scale ν at pixel coordinate z. σ signifies the

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standard deviation and $\|\cdot\|$ indicates the L_2 -norm operator. The kernel matrix $\Psi \mu \nu$ is of size $h \times w$ pixels. The symbol $k\mu, \nu = (k\nu\cos\varphi\mu, k\nu\sin\varphi\mu)^T$ represents a wave vector in which $k\nu = k_{max}/f^{\nu}$ is the frequency where k_{max} is the maximum frequency and f is the spacing between kernels in frequency domain. $\varphi\mu = \mu\pi/8 \in [0,\pi]$ specifies the orientation.

The Gabor illustration of an image matrix $X \in \mathbb{R}^{p \times q}$ is the consequence of convolving X with a Gabor kernel $\Psi \mu, \nu$. The complication can be performed in both longitudinal and frequency domains. However, we shall focus on the spatial domain convolution¹ in which the planned method is originated (see Section III for details). This intricacy can be written as:

$$0\mu\nu(x \ y) = \sum_{c=1}^{\infty} \mathbf{X}(x \ c \ y, \Sigma^{\Sigma} - , -r)\Psi\mu\nu(c,r), \quad (2)$$

where $O\mu^{\nu} \in C^{p \times q}$, (x,y) is a pixel coordinate of image X, (c,r) is a pixel coordinate of kernel $\Psi\mu^{\nu} \in C^{h \times w}$, p > h, q > w, and both h and w are odd numbers. To knob pixels falling on the image boundary, a zero padding can be adopted.

The next step is to divide magnitude and/or phase features from the $O\mu,\nu$ matrix. Except for some works to list just a few, works discarded the phase information due to its sensitivity to changes in rotation and conversion while absorbent the magnitude statistics. For similar reason, our proposed method adopts only the magnitude feature for recognition, which is defined as follows:

$$\mathbf{M}\boldsymbol{\mu}_{\boldsymbol{\nu}}\left(\boldsymbol{x},\boldsymbol{y}\right) = \sqrt{\mathrm{Re}\left(\mathbf{O}_{\boldsymbol{\mu},\boldsymbol{\nu}}\left(\boldsymbol{x},\boldsymbol{y}\right)\right)^{2} + \mathrm{Im}\left(\mathbf{O}_{\boldsymbol{\mu},\boldsymbol{\nu}}\left(\boldsymbol{x},\boldsymbol{y}\right)\right)^{2}},\quad(3)$$

where $M\mu\nu\in \mathbb{R}^{p\times q}$, $\operatorname{Re}^{(\cdot)}$ and $\operatorname{Im}^{(\cdot)}$ respectively correspond to real and imaginary parts of $O\mu\nu$.

B. TER minimization for multi-category classification

Affording to the total error rate (TER) is defined as a summation of the false receiving rate and the false rejection rate of a prognosticator's output at a assured decision threshold τ . Let N_c be the total number of classes where each class represents an identity. Then, examples belonging to the C^{th} -category, $C = 1, \dots, N_c$, are treated as positive class (represented by a superscript '+') while all the other non- C^{th} category samples are measured as negative class (represented by a superscript '-'). With an suitable regulation plus enclosure of an offset term η , minimization of TER with respective to a classifier which is linear in its limitations β_c can be solved in analytic form [41]:

 $\beta C = (bI + PCTWCPC) - 1PCTWCyC, (4)$

where *b* is a regularization factor,
$$P_C = \begin{bmatrix} \mathbf{P}_C^- \in \mathbb{R}^{m_C^- \times d} \\ \mathbf{P}_C^+ \in \mathbb{R}^{m_C^+ \times d} \end{bmatrix} \in$$

 $\mathbf{R}^{m\times d}$ is a regressor matrix, m_{C}^{*} and m_{C}^{-} $(m=m_{C}^{+}+m_{C}^{-})$ separately specify the positive class and negative class populations.

$$= \begin{bmatrix} \mathbf{y}_{C}^{-} \\ \mathbf{y}_{C}^{+} \end{bmatrix} = \begin{bmatrix} (\tau - \eta)\mathbf{1}_{C}^{-} \in \mathbb{N}^{m_{C}} \\ (\tau + \eta)\mathbf{1}_{C}^{+} \in \mathbb{N}^{m_{C}^{+}} \end{bmatrix}$$

y *_C*∈N^{*m*} is a target vector,

$$\begin{split} \mathbf{1}_{C^-} &= & [\mathbf{1}, \cdots, \mathbf{1}]^T \in \mathbb{N}^m C^- \text{ and } \mathbf{1}_C^+ &= & [\mathbf{1}, \cdots, \mathbf{1}]^T \in \mathbb{N}^m C^+ W_C = \\ \mathbf{W}_C^- &+ & \mathbf{W}_C^+ \in \mathbb{R}^{m \times m} \text{ is a diagonal weighting matrix definite for the } C \text{-th class in which } W_{C^-} = & \text{diag}(\mathbf{1}/m_{C^-}, \cdots, \mathbf{1}/m_{C^-}, \mathbf{0}, \cdots, \mathbf{0}) \\ \text{and } & W_C^+ &= & \text{diag}(\mathbf{0}, \cdots, \mathbf{0}, \mathbf{1}/m_C^+, \cdots, \mathbf{1}/m_C^+) \\ \text{personality matrix with dimension matching that of } \mathbf{P}_C^T \mathbf{P}_C. \end{split}$$



Fig1. BLOCK DIAGRAM OF FACE RECOGNITION

3. PROPOSED SYSTEM

In this section, we propose a single hidden layer feed forward network, called analytic Gabor feed forward network (AGFN), for well-organized extraction of Gabor features without needing the time consuming convolutional operation in full mode. Another important appearances of AGFN is that no iteration is needed for network training and the solution is worldwide optimal with respect to classification total error rate.

By removing redundant computations while extracting Gabor variant features at the input and the hidden layers, we achieve both efficiency and efficacy at the same time. The outputs from the hidden layer are consequently fused to produce the final decision in analytic solution. The following subsections provide details of AGFN Volume: 06 Issue: 03 | Mar 2019

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The proposed method uses a well-known face database, ORL database from the AT&T laboratories, Cambridge the design of the proposed system is as shown in Fig 1. A typical face recognition system has pre-processing, feature extraction and classification steps. In the proposed method pre-processing is done where the images are rehabilitated to matrix form, Feature extraction is done using homogeneity, energy, covariance, divergence, disproportionateness, mean, entropy, kurtosis, standard deviation, and covariance. The classification is approved out using feed forward neural network.



Fig2. Use case diagram of Face recognition



Fig3. Representation of Face recognition

3. CONCLUSION

In this paper, a single hidden layer analytic Gabor feed forward network was proposed for face recognition. Fundamentally, the input layer took in raw images and proliferated geometrically confined sub-image patches to the hidden layer. At the hidden layer, vertically and horizontally gathered Gabor magnitude features were extracted over several orientation and scale settings. After a whitening process with dimension reduction, the extracted features were finally fused at the output layer for classification decision based on the total error rate minimization. Our empirical results on CMU-PIE, FERET, Multiple, and COX datasets showed equivalent or better accurateness and CPU processing time performances than state-of-the-art and/or Gabor-based face recognition methods. Although the trivial networks are computationally efficient, their simplification ability for complex data could be limited. The proposed method trades off between such weakness and computational efficiency for solicitations in which only a single working out sample per person is obtainable.

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