

# Majority Voting In Multi-Class Domains with Biased Annotators

Lyby Thomas

Student, Dept of Dual Degree Computer Applications, Sree Narayana Guru Institute of Science and Technology

Kerala, India

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**Abstract** - Majority voting may be a popular and robust strategy to aggregate different opinions in learning from crowds, where each worker labels examples consistent with their own criteria although it's been extensively studied within the binary case, its behavior with multiple classes isn't completely clear, specifically when annotations are biased. This paper attempts to fill that gap. The behavior of the bulk voting strategy is studied in-depth in multi-class domains, emphasizing the effect of annotation bias. By means of an entire experimental setting, we show the restrictions of the quality majority voting strategy. The use of three simple techniques that infer global information from the annotations and annotators allows us to place the performance of the bulk voting strategy in context

**Key Words:** Multi-class learning, Learning from crowds, Biased annotations

## 1.INTRODUCTION

In supervised classification, a classification model is learnt from a set of labeled examples of a specific domains of that it classifies new unlabeled examples as precisely as possible. However, acquiring the classification label related to every instance for mannequin education is generally difficult and costly. Among different current proposals which center of attention on gaining knowledge of with partial classification statistics getting to know from crowds obtains (partial) classification records from a crowd of workers. Workers, a.k.a. labelers, are furnished with person examples and requested to return the

classification label which, in accordance to their opinion, every instance belongs to. The area know-how of labelers may also be decreased and their answer, therefore, noisy. This paradigm has acquired tremendous interest and, with the underlying assumption that errors are context-dependent, there already exist well established methodologies, such as these primarily based on the Expectation-Maximization method which take into account the predictive variables to concurrently infer the labeling and analyze a classification model. Other strategies work solely with the annotations in a step previous the studying stage to produce a full labeling for the coaching examples. Consequently, it can be used to analyze any classifier via well-known studying techniques. In this study, we focal point on these strategies and, amongst them, on the majority vote casting (MV) strategy, which stands out due to the fact of its simplicity: the use of the label chosen by using a majority of labelers. Its sturdy conduct underneath trendy prerequisites has been significantly depicted Furthermore, most of the modern-day research work on binary classification [8], Others declare that their crowd studying method straightforwardly extends to deal with many labels except going deeply into the actual problems of the multi-class setting. While in binary classification the labeling noise simply mixes two instructions up, with m feasible labels a labeler has ways of confusion. In this paper ,we specifically explore the difficulties of MV to deal with multi-class domains when annotations are

biased. In this context, bias, or recurrent noisy labeling, is defined as the vogue to assign label  $b$  when the actual one is  $c$ . By drawing unique situations —such a repetitive failure may also be a whole-crowd conduct or specific to positive labelers—, we purpose to describe how bias influences the MV strategy. The contributions of this paper are: (i) a find out about of the conduct of the MV method in multi-class domains with biased annotations, and (ii) an empirical learn about on actual crowd datasets.

## 2. METHODOLOGY

Formally, a supervised classification hassle [12] is described with the aid of a set of predictive variables  $X = (X_1, \dots, X_v)$  and a category variable  $C$ . Each trouble instance is an occasion  $(x, c)$  of the random vector  $(X, C)$ . Given a set of examples  $D = \{(x_1, c_1), \dots, (x_n, c_n)\}$ , a classifier is learnt. A aggressive classifier is capable to generalize from  $D$  and, given a new unlabeled example,  $(x, ?)$ , predict its category value,  $c$ . Usually, a area professional provides, from a set of viable values  $C$ , the category price  $c_j$  related to every education instance  $x_j$ . Throughout the relaxation of the paper, “class label” and “category” are interchangeably used to refer to any of the  $m = |C|$  possible values of the type variable. Learning from crowds considers a coaching dataset except specialist supervision. By contrast, a set of noisy labelers annotates every example  $:D = \{(x_1, a_1), \dots, (x_n, a_n)\}$ , the place  $a_j$  is a  $t$ -tuple with  $a_j l \in C$  indicating the classlabel assessed by using labeler  $l$  for  $x_j$ . Although eventually the goal is additionally to examine a classifier, in this paper we find out about exceptional procedures that estimate the actual  $c_j$  from  $a_j$  in a pre-process step preceding to mannequin learning, and brush aside the descriptive facts  $x_j$ . Note,

therefore, that no studying approach is regarded in this work.

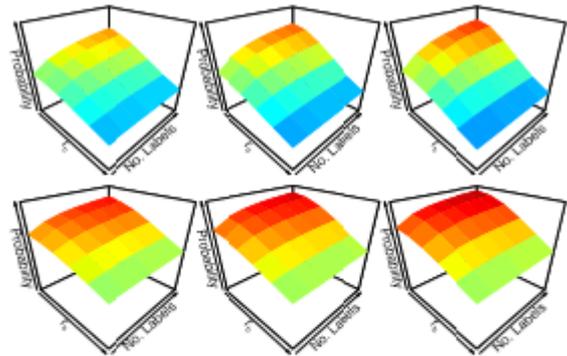


Fig. 1. Probability of success of MV (Eq. 2) when annotators tend to confuse the real category,  $c^*$ , with another label,  $b$ . Each figure shows the probability as the number of labels,  $m = \{3, \dots, 9\}$ , and the annotation bias  $r_b = \{\frac{1-r_{c^*}}{m-1}, \dots, 1-r_{c^*}\}$ , are increased. Figures are displayed by column, depending on the number of annotators,  $t = \{8, 10, 12\}$ , and by row, depending on their mean reliability,  $r_{c^*} = \{0.4, 0.5\}$ .

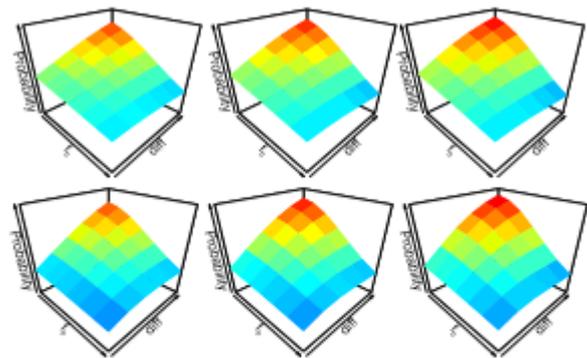


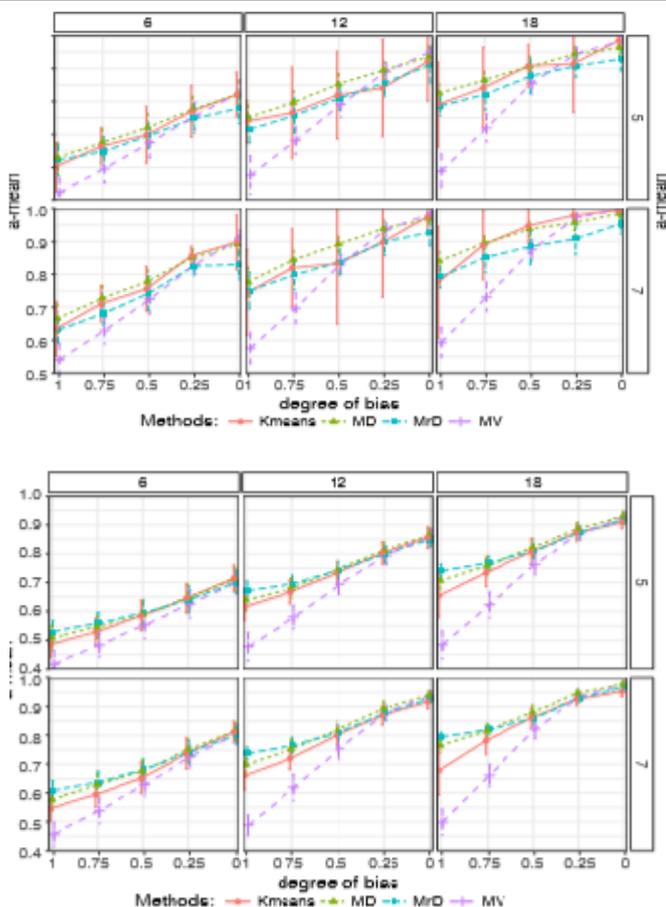
Fig. 2. Probability of success of MV (Eq. 2) when annotators tend to confuse the real category,  $c^*$ , with another label,  $b$ . A fixed difference,  $diff$ , is guaranteed between  $r_{c^*}$  and  $r_{c'}$ ,  $\forall c' \neq c^* \neq b$ . Each figure shows the probability as the difference,  $diff$ , and the bias,  $r_b = f_b \cdot r_{c^*}$  (where  $f_b = \{0, 0.25, \dots, 1.5\}$ ), are increased. Figures are displayed by column, depending on the number of annotators,  $t = \{8, 10, 12\}$ , and by row, depending on the number of labels,  $m = \{3, 9\}$ .

The most-voted label method consists of choosing the class that receives the biggest variety of votes. When solely  $m=2$  options are possible, this is equivalent to the majority balloting approach —i.e., the desire of greater than a half of of the voters. Although in multi-class getting to know ( $m > 2$ ) these are not, strictly speaking, equal strategies, for the duration of this paper and with a little abuse of language the time period “majority voting” will be used to refer to the most-voted label strategy:  $MV(\{a_1, \dots, a_t\}) = \operatorname{argmax}_{c \in C}$

$t \times l = 1 \quad I[a_l = c] \quad (1)$  where  $I[\text{cond}]$  is the indicator characteristic which returns 1 if cond is actual and zero otherwise. The chance of the MV label being the actual label  $c^*$  can be expressed as follows,  $p(c_{MV} = c^* | r) = \sum_{(o_1, \dots, o_m)}: o_{c^*} \geq o_c, \forall c \quad (P_{m \ c=1} o_c)! \ Q_{m \ c=1} o_c! \ Q_{m \ c=1} r^{o_c} \prod_{c=1}^m I[o_c = o_{c^*}] \quad (2)$  the place all the  $t$  labelers share the equal likelihood distribution  $r$  (where  $r_c$  is the chance of annotating label  $c$ ), and  $o = (o_1, \dots, o_m)$  is a tuple which counts, for every type label  $c$ , the variety of votes,  $o_c = \sum_{l=1}^t I[a_l = c]$ . MV is a easy but efficient approach with a sturdy conduct which has been mostly studied. Its overall performance is better as the variety of annotators per instance and their reliability is increased. Random errors are normally assumed although, if annotators have a tendency to confuse systematically a pair of labels (i.e., label  $b$  is commonly annotated when the actual label is  $c^*$ ), the overall performance of MV is compromised. Consider, for example, a area with a regular class and a few extra which require excessive know-how to discover the examples that belong to them. Intuition tells us that labelers can also overpopulate the ordinary category. In this case, the MV label may no longer be the actual one. According to Figure 1, the place the impact of a biased crowd on exceptional eventualities is depicted, annotation bias generally impacts, as expected, the overall performance of the MV strategy; the large the bias, the decrease the chance of MV being successful. Similarly, the affect of bias is greater when the suggest reliability of the annotators (i.e., the chance of the actual label,  $r_{c^*}$ ) decreases. Moreover, the classical trick of consulting greater annotators for enhancing MV has a bare effect when the bias is large.

Finally, the influence of bias looks to be decreased with giant numbers of viable labels,  $m$ . Note that, in this scenario, the probability of choosing label  $c_0, r_{c_0} = 1 - r_{c^*} - r_b \ m^{-2}$ , is defined primarily based on  $m$ , the reliability  $r_{c^*}$  and the chance of bias  $r_b$ . Intuitively, given fixed values for  $r_{c^*}$  and  $r_b$ , the chance of many annotators mistakenly selecting the equal label  $c_0$  decreases as  $m$  is enlarged and, consequently, the chance of success of MV would increase. As this scenario would possibly now not concur in reality, comparable figures are displayed in Figure two by means of making sure a steady difference  $\text{diff} = r_{c^*} - r_{c_0}$  between the actual type and any different label (besides the biased one,  $b$ ). Apart from the impact of the expand of  $m$ , which no longer benefits MV, comparable behaviors are found in the exceptional scenarios. Again, a large range of annotators,  $t$ , does now not usually enable MV to overcome the impact of bias; it is solely tremendous when the bias is low and the distinction between  $r_{c^*}$  and  $r_{c_0}$  is large. The MV approach solely makes use of the instance annotations for making a decision. Information about the entire dataset is integral to pick out bias. A easy approach consists of deciding on the label which receives the biggest percentage of votes in evaluation to the suggest proportions of votes

Dataset	$n$	$m$	Label distribution	$ID_{ME}$
vowel	990	11	{90×11}	0.000
segment	2310	7	{330×7}	0.000
vehicle	846	4	{212, 217, 218, 199}	0.008
svmguides4	612	6	{86, 116, 119, 99, 110, 82}	0.348
satimage	6435	6	{1533, 703, 1358, 626, 707, 1508}	0.372
dermatology	366	6	{112, 61, 72, 49, 52, 20}	0.381
pendigits	10992	10	{1142, 1143×2, 1144×2, 1055×4, 1056}	0.402
glass	214	6	{70, 76, 17, 13, 9, 29}	0.567
usps	9298	10	{1553, 1269, 929, 824, 852, 716, 834, 792, 708, 821}	0.712
arrhythmia	452	13	{245, 44, 15, 15, 13, 25, 3, 2, 9, 50, 4, 5, 22}	0.738



Results of the four aggregation functions in terms of a-mean and associated standard deviation. In the first figure, synthetic datasets are used ( $m = 5$ ) and, in the second figure, real datasets (Tab. 1). In both figures, plots are displayed by column, depending on the number of annotators,  $t = \{6, 12, 18\}$ , and by row, depending on the relevance,  $\{5, 7\}$ , of the real label. Each plot shows performance as the bias degree ( $\alpha$ ) is reduced

### 3. CONCLUSIONS

In this paper, we study the behavior of the bulk voting strategy handling biased annotations. Its lack of perspective—aggregation is performed without taking under consideration global behaviors like bias—limits its performance. Standard decisions like enlarging the amount of annotations are not efficient enough to compensate the effect of bias. These troubles may even worsen if MV is employed together with a weighted approach to estimate the reliability of annotators. Other strategies specifically designed to affect biased annotations clearly overcome MV in biased domains. Specifically, both simple approaches supported

maximum distance clothed to be notably competitive. Only simple techniques that do not consider the example descriptions ( $x$ ) were studied. However, when this information is out there (e.g., to find out a classifier), we could cash in of it. during this context, measuring to what extent the instance descriptors can enhance the estimation of the bottom truth labels would be of interest. It might be also interesting to review the robustness of the space based approaches if annotator reliability weights are introduced directly in their calculation during a similar way as wMV does with MV. Finally, an indepth study which analyzes the effect of sophistication imbalance on the behavior of the annotators and its final impact on the estimated ground truth would definitely be valuable

### ACKNOWLEDGEMENT

In the name of almighty, I would like to extend my heartfelt thanks to our HoD Mrs.Kavitha C.R, Department of a Dual Degree Master of Computer Applications for the helps extended to me throughout my course of my study. I am deeply grateful to my guide Mrs. Sony P.M Assistant Professor, Department of a Dual Degree Master of Computer Applications for the valuable guidance

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