

# SHORTEST PATH DETERMINATION FOR PUBLIC TRANSPORTATION USING SFL ALGORITHM

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**Abstract** - The Smart traffic the board is normally obliged by the elements including time productivity, assets prerequisite, and dependability of the street organization. Consequently, a keen traffic the executives utilizing picture preparing is worked with the objective of the briefest travel time and the base level of gridlock. Initially, vehicle screen module which orders and includes moving vehicles in video surges of traffic scenes recorded by fixed cameras. Besides, focal worker unit used to control traffic on streets or in broad daylight places. The traffic signal changes dependent on the information got from the vehicle screen module. Thirdly, Emergency vehicle screen module in which the crisis vehicle gets most elevated need and arrive at the objective in the briefest time. And afterward, at long last Route enhancement module it chooses dependent on the continuous and verifiable information of movement speed, an improved rearranged frog jumping calculation is intended to anticipate the movement time. On consolidating with the normal travel time, the gridlock record is characterized to gauge the unwavering quality of the course. The outcomes show that the Improved rearranged frog jump calculation addresses the issues of the different imperatives.

**Key Words:** SFLA, Numpy, Traffic management.

## 1.INTRODUCTION

### 1.1 Objective

- To ease gridlocks on streets.
- To figure out the most brief travel time to arrive at the objective prior.
- To limit the holding up season of the vehicles.

### 1.2 Need for Traffic Light Control

Traffic lights are utilized to control the progression of vehicles. In the new year's, the need of transportation has acquired huge significance for coordination's just as for normal human. This has offered ascend to the quantity of vehicles out and about. Because of this explanation, gridlocks and street mishaps are a typical sight in any bustling city. Traffic lights give a simple, modest, programmed and legitimized answer for the street focuses where the vehicles may go to different headings.

### 1.3 Drawback of Existing Technology

- The traffic signals are typically part into fixed-time spans, and the term of green/red lights must be a various of this fixed-length stretch, which isn't efficient by and large.
- The traffic signals are intended to change in an arbitrary succession, which is certainly not a safe, nor agreeable path for drivers.

## 2. ANALYSIS, DESIGN AND MODELLING

### 2.1 SFLA

Nature motivated calculations have gotten progressively well known in the new year's, and the vast majority of these metaheuristic calculations have been discovered to be exceptionally proficient. Nature enlivened calculations are the critical thinking strategies which are utilized for improvement of complex certifiable situations. These strategies are enlivened by the organic cycles which are seen from the nature. There are different sorts of nature motivated calculations specifically hereditary calculation, memetic calculation, transformative calculation, molecule swarm enhancement, and so forth.

Hereditary calculation is a strategy for settling both requirement and unconstrained improvement issues that depends on common choice, the cycle that drives natural advancement. Researchers address a wise abuse of an irregular hunt used to take care of streamlining issues. Albeit randomized, hereditary calculations are not arbitrary, rather than that abuse authentic data to coordinate the hunt into the district of better execution inside the pursuit space. The fundamental procedures of hereditary calculations are intended to invigorate measures in common frameworks essential for development, particularly those follow the standards initially set somewhere around Charles Darwin of "Natural selection". Memetic calculation is an augmentation of hereditary calculation, it utilizes nearby inquiry procedures to decrease the probability of the untimely assembly. It is a populace-based methodology whose greatness is quicker than customary hereditary calculations for some difficult spaces. In this the populace is initialized indiscriminately or utilizing a heuristic strategy. At that point, every individual makes neighborhood search to improve its wellness. To frame new populace for new age, better people are chosen.

It is produced for improvement by Muzaffar Eusuff, Kevin Lansey and Fayzul Pasha in 2003. SFLA coordinates the benefits of both the developmental methodology based memetic calculation and molecule swarm advancement calculation. SFLA depends on the advancement of images that are conveyed by people and trade of data internationally inside a populace because of communication between the people. The populace in SFLA is made out of a bunch of frogs that are coordinated into different groups, called the memeplexes. Each frog in the memeplex indicates a possible answer for a given improvement issue. Inside each memeplex, every one of the constituent frogs holds convictions that are impacted by the convictions of different frogs and developed through a cycle of memetic advancement, called the neighborhood search. Resulting to various memetic developmental advances, the memeplexes are rearranged which prompts a worldwide development. These cycles of neighborhood search and rearranging proceed till the pre-characterized assembly models are not met. SFLA right off the bat produces an underlying, arbitrary populace  $P$  of frogs  $F_i$  of size  $n$ . Subsequent to processing the wellness of the underlying arrangements, the whole populace is arranged in the dropping request of their wellness esteems. In this way, the frogs ( $F_i$ ) are partitioned into  $m$  memeplexes  $M_1, M_2, M_3 \dots M_m$  as follows:

Inside each memeplex, the wellness of most noticeably awful arrangement is improved by changing the wellness scene concurring the nearby and worldwide best arrangements.

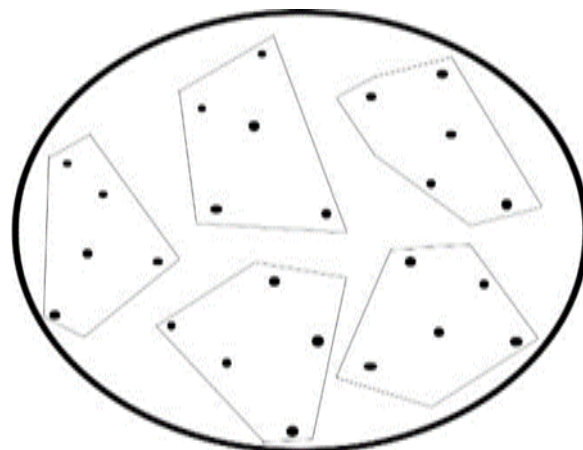


Fig -1: Structure of SFLA

In Figure 1 shows the structure of SFLA in which five routes were joined together which is called memeplex.

## 2.2 OVERALL ARCHITECTURE WITH COMPONENT DESCRIPTION

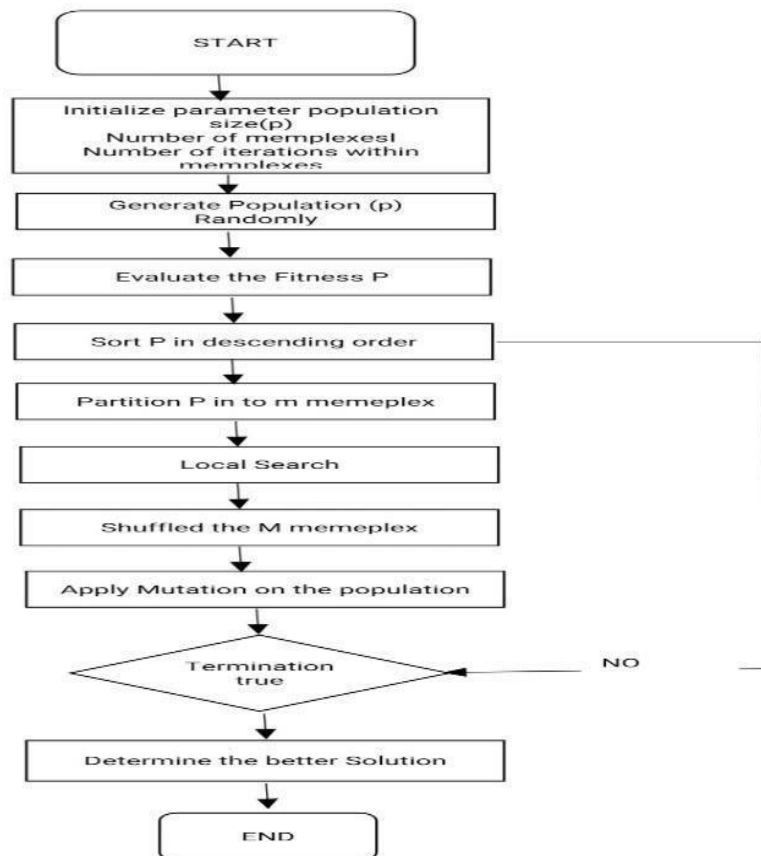


Fig -2: Flowchart for SFLA

## 2.3 ORIGINAL SFLA

Beginning from exemplary SFLA, it is a meta-heuristic drew closer for tackling complex true issues, it is a nature propelled agreeable for a given populace. A populace is as set of people. Every individual has a related wellness esteem that estimates how close it is from food. SFLA comprises of a bunch of frogs partitioned into certain memplexes. The calculation depends on the development of images conveyed by the iterative people, and a worldwide trade of data among themselves.

Let's examine the interaction through arrangement of steps:

1. Initialize the number of inhabitants in the frogs of size of P.
2. Ascertain the wellness of the multitude of frogs of populace and sort them in climbing request of their wellness. The wellness is the benchmark for enhancement i.e., the lower its worth the more advanced it is. It is utilized to assess the situation of frog.
3. Divide the frog populace into m memplex for each containing N frogs. Conveyance would resemble first frog goes to first memplex, second frog goes into second memplex, etc.
4. Perform the nearby looking inside the each memplex. Let the frog with the best wellness is  $X_b$  and the frog with the most exceedingly terrible wellness is  $X_w$  individually. The worldwide best frog is addressed by  $X_g$ .  $X_w$  gets refreshed by  $X_g$  as follows:  $X_w' = X_w + r.(X_b - X_w)$
5. where 'r' is arbitrary number in range (0,1). Need to do it under specific requirements:  $|X_b - X_w| < D_{max}$ , where  $D_{max}$  is the greatest conceivable difference in frog. In the event that the above condition upgrades the most noticeably awful frog position towards best territory, the wellness work is refreshed correspondingly. Else, the  $X_b$  boundary in the above condition is supplanted with the worldwide best frog ( $X_g$ ) and again its wellness isn't not exactly the most exceedingly awful frog wellness at that point,  $X_w$  is supplanted by the frog which is haphazardly

created with subjective wellness.

In the wake of finishing the nearby pursuit inside the memeplex, all the populace are rearranged and the worldwide data are died those frogs in the rearranged interaction.

6. Local hunt and rearranging measure proceed with fill the particular models is statistical.

**2.4 IMPROVED SFLA USING MEMETIC RECONFIGURATION**

As of now talked about different calculations or strategies which are improving the outcomes. A few calculations, proposed are improving the assembly rate inside the memeplex. A portion of the calculations depended on the Orthogonal learning. Some have conveyed forward their work on memetic advancement, which prompts quicker combination by creating intelligent learning strategies, in which the most exceedingly terrible frog position improved utilizing the frogs past encounters in each measurement. One of the procedures depended on refreshing the neighborhood search venture by allotting the estimation of irregular in the scope of (0,2). This implies that the refreshed most exceedingly terrible frog wellness can be superior to the best frog wellness, hence staying away from the combination trap.

Out of every one of these, designers can see that none of them have done their work on reconfiguration of memeplex. How about we presently expound our contemplations on what do one mean by reconfiguration of memeplexes. Expecting there are (m=5) memeplexes and populace size (P=25). Presently we should comprehend the dispersion of the frogs in exemplary SFLA calculation with figure appeared underneath:

F1	F2	F3	F4	F5
F6	F7	F8	F9	F10
F11	F12	F13	F14	F15
F16	F17	F18	F19	F20
F21	F22	F23	F24	F25

Fig -3: SFLA (Row wise distribution)

In our calculation, need to change the request for frogs as demonstrated underneath:

F1	F6	F11	F16	F21
F2	F7	F12	F17	F22
F3	F8	F13	F18	F23
F3	F9	F14	F19	F24
F5	F10	F15	F20	F25

Fig -4: SFLA (Column wise distribution)

Broadening our work on additional level, for that dispersing the frogs in memeplex arbitrarily as demonstrated in figure beneath:

F1	F6	F11	F16	F21
F2	F7	F12	F17	F22
F3	F8	F13	F18	F23
F3	F9	F14	F19	F24
F5	F10	F15	F20	F25

**Fig -5:** SFLA (Random distribution)

Finally check the trial consequences of the proposed calculation with differentiation to exemplary SFLA. The need to analyze most exceedingly awful frog, best frog, middle, standard deviation and mean for the end rules allocated.

### 3. SOFTWARE DESCRIPTION

#### 3.1 Python

Python is a broadly useful programming language began by Guido van Rossum, which turned out to be extremely mainstream in brief time frame predominantly in view of its straightforwardness and code intelligibility. It empowers the software engineer to communicate his thoughts in less lines of code without decreasing any lucidness.

Contrasted with different dialects like C/C++, Python is slower. In any case, another significant component of Python is that it tends to be handily reached out with C/C++. This element assists with composing computationally serious codes in C/C++ and make a Python covering for it so designers can utilize these coverings as Python modules.

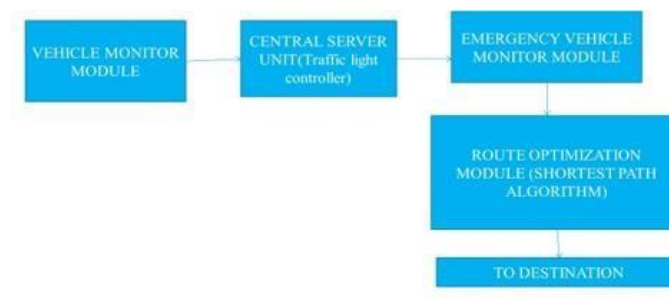
This gives two benefits: first, our code is just about as quick as unique C/C++ code (since it is the real C++ code working in foundation) and second, it is not difficult to code in Python. This is the manner by which OpenCV-Python works, it is a Python covering around unique C++ usage. What's more, the help of Numpy makes the errand simpler.

Numpy is an exceptionally improved library for mathematical activities. It gives a MATLAB-style language structure. All the OpenCV cluster structures are changed over to and from Numpy exhibits. So whatever activities you can do in Numpy, you can consolidate it with OpenCV, which builds number of weapons in your stockpile. Other than that, few different libraries like SciPy, Matplotlib which underpins Numpy can be utilized with this. So OpenCV-Python is a proper device for quick prototyping of PC vision issues.

### 4. SYSTEM IMPLEMENTATION

#### 4.1 Overall Block Diagram

Figure 6 explains three main modules, Vehicle monitor module, Emergency vehicle monitor module and Route optimization module



**Fig -6:** Overall Block Diagram

## 4.2 Vehicle Monitor Module

Figure 6 explains the flowchart of vehicle monitor module. Initially the image of the empty road gets collected and further it captures the image with the vehicles on the road. On fixing the threshold value the initial empty road and the final image gets compared to find the difference between these two frames and further the image is converted from grayscale to binary to count the number of vehicles available in the particular lane.

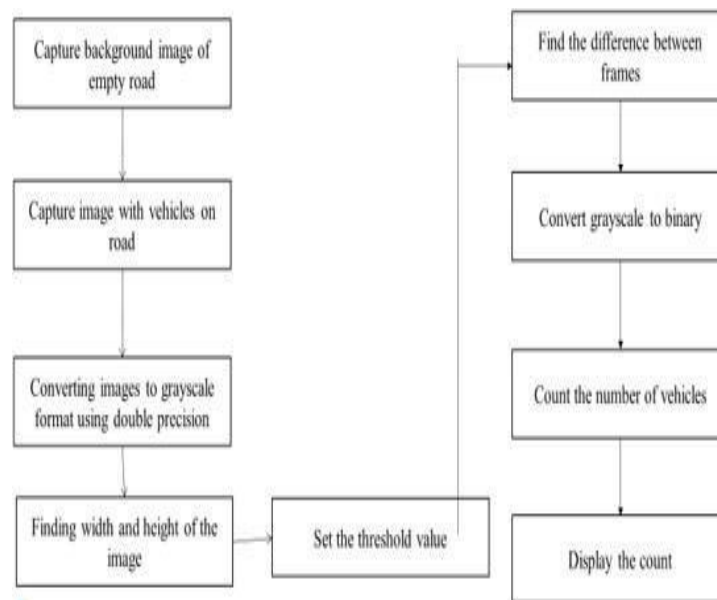


Fig -7: Vehicle Monitor Module

## 4.3 Emergency Vehicle Monitor Module

In case if an emergency vehicle is approaching the specific lane then that emergency vehicle should send priority request to the traffic light controller. On receiving the accepted request from the traffic light controller then the emergency vehicle is allowed to move in the specific lane otherwise it should wait until it gets positive request.

## 4.4 Route Optimization Module

In this module the main concept of the vehicle is to reach the destination in a shortest path. The shortest path is identified with the improved shuffled frog leap algorithm. This helps all the vehicle to reach its destination very fast and it is especially used for emergency vehicles.

## 4.5 Central Server Unit

This unit is connected with the both vehicles monitor module and emergency vehicle monitor module, hence this unit is named as Central server unit. The vehicle counts from the vehicle monitor module is used for dynamic adjustments of the traffic lights. And the emergency vehicle monitor module is communicated with the traffic light controller to get special attention to reach its destination.

## 5. RESULTS

### 5.1 Vehicle Detection and Counting

In Figure 8 shows the vehicles in a particular lane is detected and the vehicle count is displayed. Python 3.7 is used for performing image processing.



Fig -8: Results for vehicle detection and counting

In Straight road, all the vehicles get detected and the vehicle count is instructed to the central server unit (Traffic light controller). This unit further helps in functioning of the traffic light dynamically to avoid accidents and to avoid congestions.

### 5.2 Calculating Shortest Path

Figure 9 shows the optimal path. Initially 25 routes are available in between the source and the destination. With the minimal of 5 routes is divided and named as memeplex. From this each memeplex best, worst and the global routes are identified which finally results in identifying best optimal route to reach the destination.

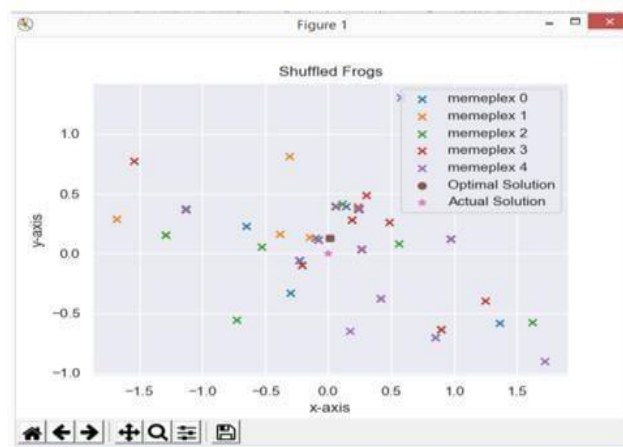
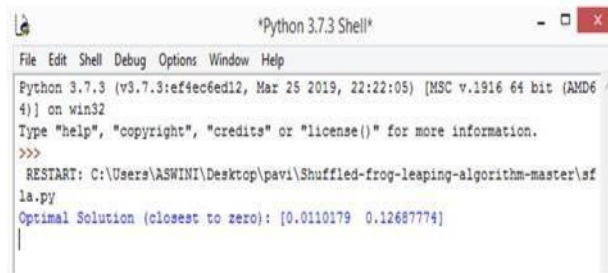


Fig -9: Results for finding shortest path

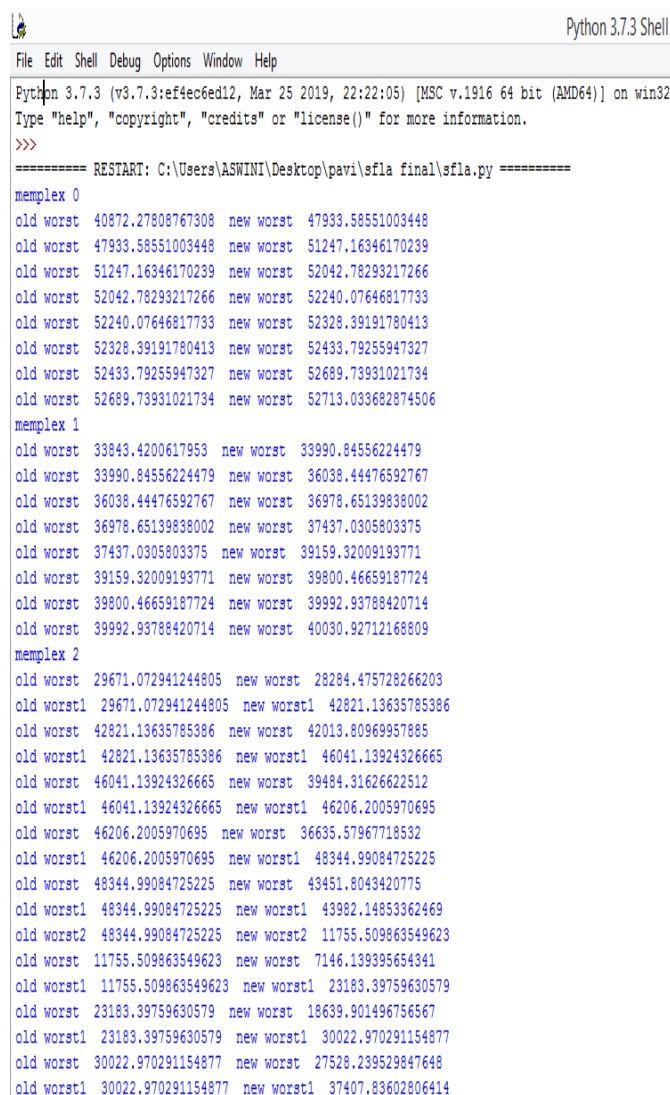




```
Python 3.7.3 (v3.7.3:ef4ec6ed12, Mar 25 2019, 22:22:05) [MSC v.1916 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>>
RESTART: C:\Users\ASWINI\Desktop\pavi\Shuffled-frog-leaping-algorithm-master\sfla.py
Optimal Solution (closest to zero): [0.0110179 0.12687774]
```

Fig -10: Results for finding optimal solution

In Figure 10 the optimal solution to reach destination is found alongwith the x and y coordinates.



```
Python 3.7.3 (v3.7.3:ef4ec6ed12, Mar 25 2019, 22:22:05) [MSC v.1916 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>>
===== RESTART: C:\Users\ASWINI\Desktop\pavi\sfla final\sfla.py =====
memplex 0
old worst 40872.27808767308 new worst 47933.58551003448
old worst 47933.58551003448 new worst 51247.16346170239
old worst 51247.16346170239 new worst 52042.78293217266
old worst 52042.78293217266 new worst 52240.07646817733
old worst 52240.07646817733 new worst 52328.39191780413
old worst 52328.39191780413 new worst 52433.79255947327
old worst 52433.79255947327 new worst 52689.73931021734
old worst 52689.73931021734 new worst 52713.033682874506
memplex 1
old worst 33843.4200617953 new worst 33990.84556224479
old worst 33990.84556224479 new worst 36038.44476592767
old worst 36038.44476592767 new worst 36978.65139838002
old worst 36978.65139838002 new worst 37437.0305803375
old worst 37437.0305803375 new worst 39159.32009193771
old worst 39159.32009193771 new worst 39800.46659187724
old worst 39800.46659187724 new worst 39992.93788420714
old worst 39992.93788420714 new worst 40030.92712168809
memplex 2
old worst 29671.072941244805 new worst 28284.475728266203
old worst1 29671.072941244805 new worst1 42821.13635785386
old worst 42821.13635785386 new worst 42013.80969957885
old worst1 42821.13635785386 new worst1 46041.13924326665
old worst 46041.13924326665 new worst 39484.31626622512
old worst1 46041.13924326665 new worst1 46206.2005970695
old worst 46206.2005970695 new worst 36635.57967718532
old worst1 46206.2005970695 new worst1 48344.99084725225
old worst 48344.99084725225 new worst 43451.8043420775
old worst1 48344.99084725225 new worst1 43982.14853362469
old worst2 48344.99084725225 new worst2 11755.509863549623
old worst 11755.509863549623 new worst 7146.139395654341
old worst1 11755.509863549623 new worst1 23183.39759630579
old worst 23183.39759630579 new worst 18639.901496756567
old worst1 23183.39759630579 new worst1 30022.970291154877
old worst 30022.970291154877 new worst 27528.239529847648
old worst1 30022.970291154877 new worst1 37407.83602806414
```

Fig -11: Results for finding best and worst frogs for memplex 0,1 and 2



```
Python 3.7.3 Shell
File Edit Shell Debug Options Window Help
old worst1 23183.39759630579 new worst1 18639.901496756567
old worst1 23183.39759630579 new worst1 30022.970291154877
old worst1 30022.970291154877 new worst1 27528.239529847648
old worst1 30022.970291154877 new worst1 37407.83602806414
memplex 3
old worst1 25131.553014402645 new worst1 23107.262778350523
old worst1 25131.553014402645 new worst1 42553.548362404
old worst1 42553.548362404 new worst1 40533.454283765226
old worst1 42553.548362404 new worst1 46913.48699462792
old worst1 46913.48699462792 new worst1 36306.258503157245
old worst1 46913.48699462792 new worst1 42975.79098876011
old worst2 46913.48699462792 new worst2 14798.362630882713
old worst1 14798.362630882713 new worst1 12318.839237300324
old worst1 14798.362630882713 new worst1 30883.902567327594
old worst1 30883.902567327594 new worst1 29142.31013866677
old worst1 30883.902567327594 new worst1 36749.43330630392
old worst1 36749.43330630392 new worst1 30554.496682715508
old worst1 36749.43330630392 new worst1 45539.28202697491
old worst1 45539.28202697491 new worst1 32425.59944440803
old worst1 45539.28202697491 new worst1 36845.70461159345
old worst2 45539.28202697491 new worst2 17655.31816390821
old worst1 17655.31816390821 new worst1 18663.679584228114
memplex 4
old worst1 13830.279270379591 new worst1 13525.272906757042
old worst1 13830.279270379591 new worst1 23913.975690916403
old worst1 23913.975690916403 new worst1 19063.54393531149
old worst1 23913.975690916403 new worst1 29329.2075019471
old worst1 29329.2075019471 new worst1 28405.01804063629
old worst1 29329.2075019471 new worst1 40495.90777942388
old worst1 40495.90777942388 new worst1 24414.55253249791
old worst1 40495.90777942388 new worst1 33985.77295934045
old worst2 40495.90777942388 new worst2 21985.6712930601
old worst1 21985.6712930601 new worst1 22854.130814963493
old worst1 22854.130814963493 new worst1 22264.062241560412
old worst1 22854.130814963493 new worst1 29136.246093743266
old worst1 29136.246093743266 new worst1 25345.633294477033
old worst1 29136.246093743266 new worst1 38454.71573746637
old worst1 38454.71573746637 new worst1 28963.470988435416
old worst1 38454.71573746637 new worst1 34835.90282406144
old worst2 38454.71573746637 new worst2 8915.459780691235
>>>
```

**Fig -12:** Results for finding best and worst frogs for memplex 3 and 4

## 6. CONCLUSION

This paper gives a summing up investigation on the proposed procedures which have utilized in rush hour gridlock video. It centers in these regions, to be specific vehicle location, following, and order. The paper presents a calculation to locate the most brief way for self-sufficient vehicle conveyance issue. The introduced calculation is achievable through the approval case. Additionally, introduce and order the traffic reconnaissance frameworks to three kinds dependent on explicit strategies which utilized for creating it. These sorts show the nitty gritty data about how the traffic reconnaissance frameworks utilized the picture preparing strategies and examination apparatuses for recognize, fragment, and track the vehicles. The test result shows based on this paper vehicles identify and following in rush hour gridlock video have great versatility. In video picture vehicles find the position, gauge the movement of masses and follow the developments between two successive casings. The outcome presents that the Frame contrast technique distinguishes the presence of moving item by thinking about the distinction between two successive edges. The customary methodology utilizes picture deduction administrator that gets yield picture by taking away second picture outline from first picture outline in comparing successive edges. Casing differencing strategy needs getting the total form of the article because of which morphology activities are general used to get better outcomes.

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